## 5/2 Introduction
- Communication overview
- System components
- IO-Link specification

## 5/9 Masters
- IO-Link master module for S7-1200
- CM 4xIO-Link
- IO-Link master modules for ET 200S
- IO-Link 4SI electronic modules
- IO-Link master modules for ET 200eco PN

## 5/15 Input modules
- General data
- IO-Link K20 modules

## 5/18 Contactors and contactor assemblies
- SIRIUS 3RT20 contactors, 3-pole, 3 ... 18.5 kW
- SIRIUS 3RA23 reversing contactor assemblies
- SIRIUS 3RA24 contactor assemblies for wye-delta starting
- SIRIUS 3RA27 function module for IO-Link

## 5/26 SIRIUS 3RB24 solid-state overload relays for IO-Link
- 3RB24 for IO-Link, up to 630 A for High-Feature applications
- Current measuring modules
- Accessories

## 5/33 SIRIUS 3RA6 compact starters
- SIRIUS 3RA64, 3RA6S compact starters for IO-Link
- Accessories for compact starters for IO-Link

## 5/36 SIRIUS 3RR24 monitoring relays for mounting onto 3RT2 contactors for IO-Link
- General data
- Current and active current monitoring

## 5/43 SIRIUS 3UG48 monitoring relays for stand-alone installation for IO-Link
- General data
- Line monitoring
- Voltage monitoring
- Current monitoring
- Power factor and active current monitoring
- Residual current monitoring
- 3UL23 residual-current transformers
- Speed monitoring
- Accessories

## 5/44 SIRIUS 3RS14, 3RS15 temperature monitoring relays for IO-Link
- General data
- Relays, digitally adjustable for 1 sensor
- Relays, digitally adjustable for up to 3 sensors
- Accessories

## 5/60 RFID systems
- SIMATIC RF210R
- SIMATIC RF220R
- SIMATIC RF260R
IO-Link
Introduction

Communication overview

Overview
IO-Link is an open communication standard for sensors and actuators – defined by the Profinet User Organization (PNO). IO-Link technology is based on the point-to-point connection of sensors and actuators to the control system. Parameter and diagnostics data are transmitted in addition to the cyclic operating data for the connected sensors/actuators. The simple, unshielded three-wire cable customary for standard sensors is used for this purpose.

Benefits

Engineering
- Standardized, open system for greater flexibility (non-Siemens IO-Link devices can be integrated in engineering)
- Uniform, transparent configuring and programming through integrated engineering (SIMATIC STEP 7)
- Unassigned SIMATIC function blocks for easy parameterization, diagnostics and read-out of measured values
- Efficient engineering thanks to pre-integration into SIMATIC HMI
- Low error rate in CAD circuit diagram design as a result of reduced control current wiring

Installation and commissioning
- Faster assembly with minimized error rate as a result of reduced control current wiring
- Less space required in the control cabinet
- Low-cost circuitry where there are several feeders by making full use of existing components

Operation and maintenance
- High transparency in the system right down to field level and integration into power management systems
- Reduction in downtimes and maintenance times thanks to system-wide diagnostics and faster fault correction
- Support of predictive maintenance
- Shorter changeover times, even for field devices, by means of parameter and recipe management

Application
IO-Link can be used in the following main applications:
- Easy connection of complex IO-Link sensors/actuators with a large number of parameters and diagnostic data to the control system
- Replacement of sensor boxes for connecting binary sensors with the IO-Link input modules optimized in terms of cabling
- Optimized cable connection of switching devices to the control system
- Simple transmission of energy values from the device to the control system for integration into a user program or power management

In these cases, all the diagnostics data are transmitted to the higher-level control system through IO-Link. The parameter settings can be changed during operation. Central data storage means that it is possible to exchange an IO-Link sensor/actuator without a PC or programming device.

Integration in STEP 7
Integration of the device configuration in the STEP 7 environment guarantees:
- Quick and easy engineering
- Consistent data storage
- Quick localization and rectification of faults
To implement communication, a system installation has the following main components:

- An IO-Link master
- One or more IO-Link devices, such as sensors (e.g. RFID systems), actuators or combinations thereof
- A standard 3-wire sensor/actuator cable
IO-Link
Introduction
System components

Overview (continued)

Compatibility of IO-Link

IO-Link guarantees compatibility between IO-Link-capable modules and standard modules as follows:

- IO-Link sensors can be operated both on IO-Link modules (masters) and standard input modules.
- IO-Link sensors/actuators as well as today’s standard sensors/actuators can be used on IO-Link masters.
- If conventional components are used in the IO-Link system, then of course only the standard functions are available at this point.

Analog signals

Another advantage of IO-Link technology is that analog signals are digitized already in the IO-Link sensor itself and are digitally transmitted by the IO-Link communication. As the result, faults are prevented and there is no extra cost for cable shielding.

Enhanced through IO-Link input modules

IO-Link compatibility also permits connection of standard sensors/actuators, i.e. conventional sensors/actuators can also be connected to IO-Link. This is particularly effective with the IO-Link input modules, which allow several sensors to be connected at one time via a cable to the controller.

Load feeders and motor starters

Through IO-Link it is possible to control not only sensors but also actuators in the form of load feeders and motor starters.

Groups of motor starters

The SIRIUS controls allow four starters to be combined to form a group.

Connection of a motor starter group made up of three 3RA64 direct-on-line starters and a 3RA65 reversing starter

In this way up to 16 starters can be operated on a single IO-Link master. This leads to a reduction in the installation space and control wiring required.
Monitoring relays

By using monitoring relays with IO-Link it is now possible to send data that has already been recorded and evaluated in the devices directly to the controller. This avoids the use of duplicated sensors.

Possibilities for connecting monitoring relays to IO-Link or in the conventional way
Using an upstream IWLAN client module, such as SCALANCE W722-1 RJ45, allows IO-Link to be integrated into the PROFINET world via a distributed I/O. Possible uses include acting as an alternative to fault-prone cable carrier or collector wire technology. The individual diagnostics options offered by the various IO-Link devices provide greater transparency for the production process. Just like the parameter data for a device, these diagnostics data can be evaluated remotely using the possibilities offered by SIMATIC. This supports remote maintenance down to the lowest level in the field.

Wireless communication between Industrial Ethernet and IO-Link components
Introduction

System components

Overview (continued)

IO-Link components

IO-Link master, software, cables

Masters
- IO-Link masters for S7-1200
  - SM1278 4xIO-Link
  See page 5/9
- IO-Link master modules for ET 200SP
  - CM 4xIO-Link
  See page 5/10
- IO-Link master modules for ET 200S
  - IO-Link 4SI electronic modules
  - SIRIUS 4SI electronic modules
  See pages 5/13
- IO-Link master modules for ET 200eco PN
  See page 5/14.

Software

STEP 7 PCT
Engineering software for configuring the IO-Link master modules for S7-1200, ET 200SP, ET 200S, ET 200eco
- Available as a stand-alone version or integrated into STEP 7 (V5.5 SP1 or later) and TIA (V12 or later)
- Retrieval of parameter and diagnostics data from the IO-Link devices connected to the master
- Monitoring of the process image of the IO-Link devices
- Open interface for importing further IODDs
- Freely available for download from Industry Online Support.

IO-Link Call function block
STEP 7 function block for easy acyclical data exchange in the user program
- Freely available for download from Industry Online Support.

WinCC flexible template project
Easy integration of IO-Link devices into the user program by using ready-made WinCC flexible templates
- Freely available for download from Industry Online Support.

IODD files
IO-Link Device Description (IODD) files provide the device description for IO-Link
- Comprehensive IODD catalog of SIEMENS IO-Link devices
- Freely available for download from Industry Online Support.

Cable
3-wire standard cable
see for example catalog ID 10 “Industrial Identification Systems”

IO-Link devices (continued)

IO-Link devices

IO-Link RFID systems
SIMATIC RF200 RFID system in the HF range
- SIMATIC RF210R, SIMATIC RF220R, SIMATIC RF260R products
- Simple identification tasks (read-only), such as reading an ID number
- No RFID-specific programming, ideal for those new to RFID
- Simple connection via master modules for IO-Link, such as SIMATIC ET 200S and ET 200eco
- Use with the tried and tested ISO 15693 transponders (MOBY D) see Catalog ID 10 “Industrial Identification Systems”

Switching with IO-Link

Contacts and contactor assemblies
Power contactors for switching motors
- SIRIUS 3RT2 contactors, 3-pole, up to 18.5 kW
See page 5/11
- Contactor assemblies
  - SIRIUS 3RA23 reversing contactor assemblies
  - SIRIUS 3RA24 contactor assemblies for wye-delta starting
See page 5/22
- SIRIUS 3RA27 function modules for IO-Link
  - For direct-on-line starters, reversing starters and wye-delta starters
See page 5/24

Motor starters for use in the control cabinet
SIRIUS 3RA6 compact starters
- 3RA64 direct-on-line starters
- 3RA65 reversing starters
- Infed system for 3RA6
see page 5/33

Contactors with IO-Link

Overload relays
SIRIUS 3RB24 solid-state overload relays for IO-Link
- Evaluation module
- Current measuring modules from 0.3 to 630 A
- Controlling direct-on-line, reversing and star-delta starters via IO-Link in conjunction with contactors
- Full motor protection
- Diagnostics and current value transmission via IO-Link
See page 5/26

Monitoring with IO-Link

SIRIUS 3RR24 monitoring relays for IO-Link
- Monitoring of current, phase failure, open circuit and phase sequence
- Designed for mounting on 3RT2 contactors
See page 5/36

SIRIUS 3UG48 monitoring relays for IO-Link
- Monitoring network, voltage, current, cos φ, residual current or speed depending on device design
- On-tripping delay time can be adjusted
See page 5/43

SIRIUS 3RS14, 3RS15 temperature monitoring relays for IO-Link
- Temperature monitoring with connected sensors
- Two limit values, can be adjusted separately
See page 5/54

Detection with IO-Link

IO-Link input modules
K20 input module
- 4 inputs, M12 connections
- 8 inputs, standard M8 connections
See page 5/15

SIRIUS 3RR24 monitoring relay
SIRIUS 3UG48 monitoring relay
SIRIUS 3RS14 temperature monitoring relay

SIRIUS 3RA2711 function module for IO-Link
SIRIUS 3RA64 direct-on-line starter
SIRIUS 3RB24 overload relay
SIRIUS 3RA6 compact starters
SIRIUS 3RA65 reversing starters
Infed system for 3RA6
SIRIUS 3RR24 monitoring relay
SIRIUS 3UG48 monitoring relay
SIRIUS 3RS14 temperature monitoring relay

IO-Link
Introduction

IO-Link specification

Overview

Principles of the IO-Link specification

According to the IO-Link specification, communication functions as follows:

- Transmission takes place via an unshielded three-wire cable no more than 20 m long, of the kind normally used for standard sensors.
- Analog values which have already been digitized are transmitted in the form of message frames, which may correspond to ±10 V or 4 to 20 mA.
- Digital communication from 0 to 24 V on the so-called C/Q cable
- Most of the values transmitted are measured values from the sensors which include the units.
- The sensors and actuators are described by the IO-Link Device Description (IODD).
- While the IO-Link specification permits an infinite number of ports, an IO-Link master currently only supports four ports. Only one IO-Link device (slave) can be connected to each port (point-to-point connection).
- The transmission rates between IO-Link master and the devices are as follows:
  - via COM1: 4 800 Bd
  - via COM2: 38 400 Bd
  - via COM3: 230 400 Bd
- The average cycle time is 2 ms for the reading/writing of 16 data bits at a transmission rate of 38 400 Bd.

IO-Link protocol

For the dialog between device and master, IO-Link uses a standard protocol, the standard asynchronous communication interface (UART) in “semi-duplex” mode.

The IO-Link protocol supports both the Standard IO mode (SIO) and the IO-Link communication mode (COM).

Interface hardware:

Compatible with sensors according to IEC 60947-5-2 and actuators Communication and switching possible alternately

![IO-Link master and IO-Link device diagram]

The structure of the protocol and its message frames depends on the types of data to be transmitted.

Data types

In the IO-Link specification a distinction is made between the following data types:

Process data

The process data of the devices are transmitted cyclically in a data frame, provided the process data width does not exceed 2 bytes. In the case of larger process data widths up to 32 bytes, parts are transmitted one after the other in several cycles. As of Version 1.1 of the specification, up to 32 bytes of process data can be transferred in a single cycle.

Service data (SD)

With the aid of the service data, parameter values or device statuses can be read out. It is also possible to write the parameter values or transmit commands via the service data. Service data are always exchanged acyclically and in response to an inquiry from the IO-Link master.

Events

Via events it is possible to transmit device events or statuses such as contamination, overheating, short circuits etc., from the device via the IO-Link master to the PLC or to visualize them.

The events are sent on the initiative of the devices via the “event flag”, which the master evaluates. The master itself can also generate events.

Three categories of event are defined:

- Error signals (errors)
- Maintenance data (warnings)
- Device functions (notifications)

Data storage

As of Specification V1.1, a data storage concept has been created for IO-Link. In this concept, the IO-Link device initiates the storage of its data on a higher-level parameter server. In the event that a device is replaced, the parameter server can restore the original parameterization. It is therefore possible to replace the devices without re-parameterization.

The IO-Link master can contain the parameter server. The parameter server can also be implemented centrally in the PLC or in a system server. In this case the IO-Link master passes on the corresponding information.

IO-Link master

The IO-Link master is the interface to higher-level control systems. The IO-Link master presents itself as a normal fieldbus node, and is integrated into the appropriate network configurator via the relevant device description (e.g. GSD, FDCML, EDS etc.).

IO-Link Device Description (IODD)

The IO-Link Device Description (IODD) has been defined to provide a full, transparent description of system characteristics as far as the IO-Link device. It is based on the open XML standard.

The IODD contains information on communication characteristics, device parameters, identification, process and diagnostics data, and is supplied by the manufacturer. The design of the IODD is the same for all devices from all manufacturers, and is always presented in the same way by the IODD Interpreter Tools. This therefore ensures that the handling is the same for all IO-Link devices, whatever the manufacturer.

New in IO-Link Specification V1.1

The IO-Link Specification is currently available in Version 1.1, and standardized in accordance with IEC 61131-9. Specification V1.1 offers the following new features compared with the previous Specification V1.0:

- Transmission of up to 32 bytes of process or service data in one cycle
- Data storage concept
### Overview

**SM 1278 4xIO-Link master**

The SM 1278 4xIO-Link master signal module is an IO-Link master, and can be used in the SIMATIC S7-1200 automation system.

**Features**

- IO-Link master according to IO-Link specification V1.1
- Up to four IO-Link devices (3-wire connections) can be connected to each IO-Link master module.
- Data transmission rates COM1 (4.8 kBd), COM2 (38.4 kBd), COM3 (230.4 kBd), automatic adjustment to the transmission rate supported by the device
- Port-by-port parameterizable diagnostics
- Up to eight IO-Link master modules can be used depending on the SIMATIC S7-1200 CPU in use.

**Central data storage**

The device parameters are kept in the master module according to the specification V1.1.

**Note:**

When the SM 1278 4xIO-Link master module is exchanged, the IO-Link parameter data are not assigned automatically.

### Configuration

**Module integration**

To integrate the module you need the STEP 7 V13 TIA Portal engineering tool.

**Configuration**

S7-PCT V3.2 and higher is required in addition for IO-Link configuration.

PROFINET configuration with SIMATIC S7-1200 CPU and ET 200S distributed I/O with IO-Link master modules

The address areas for exchanging the cyclic data (process values) are defined by IO-Link in the device view of the PROFINET device.

### Selection and ordering data

<table>
<thead>
<tr>
<th>Version</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>SM 1278 4xIO-Link master signal modules</td>
<td>6ES7278-4BD32-0XB0</td>
</tr>
</tbody>
</table>

**More information**


**Manuals**


**Industry Mall**

More information see Industry Mall at “Automation Technology” ⇒ “Industral Communication” ⇒ “IO-Link” ⇒ “Masters” ⇒ “IO-Link Master Module for S7-1200”
IO-Link
Masters
IO-Link master module for ET 200SP

CM 4xIO-Link

Overview

The CM 4xIO-Link communication module is the IO-Link master, for use in the ET 200SP distributed I/O system.

Features
- IO-Link master as serial communication module with 4 ports according to IO-Link specification V1.1
- Module exchange with automatic data recovery without engineering for IO-Link master and IO-Link device
- Up to four IO-Link devices (3-wire connections) can be connected to each IO-Link master module.
- Data transmission rates COM1 (4.8 kBd), COM2 (38.4 kBd), COM3 (230.4 kBd), automatic adjustment to the transmission rate supported by the device
- Port-by-port parameterizable diagnostics
- PROFIenergy support
- Parameterization of IO-Link parameters by S7-PCT V3.0 and higher

Central data storage
If the communication module is pulled off the BaseUnit, part of the electronic coding element will remain in the BaseUnit. Stored in this part are the parameters of the CM 4xIO-Link and the parameters of the IO-Link devices. When a new (not yet parameterized) IO-Link master is plugged on, it will adopt the parameters from the electronic coding element.

Connection
All type A0 BaseUnits can be used for the CM 4xIO-Link communication module, i.e. all variants of the BaseUnit (without/with infeed, -AUX).

Configuration
Module integration
To integrate the module you need the engineering tool STEP 7 V5.5 and higher or STEP 7 V11 TIA Portal.

Configuration
S7-PCT V3.0 and higher is required in addition for IO-Link configuration.

The following diagram shows a PROFINET configuration in which PROFINET ET 200SP and ET 200eco PN devices are integrated with IO-Link masters.

Configuration of a PROFINET network with lower-level IO-Link masters
The address areas for exchanging the cyclic data (process values) are defined by IO-Link in the device view of the PROFINET device.

Device view with setting of the address range by IO-Link via TIA Portal
## Selection and ordering data

### CM 4xIO-Link communication modules
- IO-Link master for SIMATIC ET 200SP, can be plugged onto BaseUnit
- Corresponds to IO-Link specification V1.1
- Dimensions (W × H × D / mm): 15 × 100 × 75

**Article No.:** 6ES7137-6BD00-0BA0

## Accessories

### BaseUnit
- BaseUnit BU15-P16+A10+2D for CM 4xIO-Link to SIMATIC ET 200SP
- For opening a new voltage group via the plugged-in peripheral module
- Current carrying capacity per process terminal max. 2 A

**Article No.:** 6ES7193-6BP20-0DA0

## More information

### Manuals

### Industry Mall
For more information see Industry Mall at "Automation Technology" → "Industrial Communication" → "IO-Link" → "Masters" → "IO-Link Master Module for ET 200SP".
IO-Link Masters
IO-Link master modules for ET 200S

4SI IO-Link electronic modules

Overview

The 4SI IO-Link electronic module is an IO-Link master and enables easy integration of sensors and actuators from different manufacturers in the SIMATIC ET 200S multifunctional, distributed I/O system at a total of four ports.

Features

- Up to four IO-Link devices (3-wire connection) can be connected to each IO-Link master module. 3RA6 compact starters or load feeders with 3RA27 function modules can even be bundled in groups of four devices on one IO-Link port. It is possible therefore to connect up to 16 load feeders to the control system at one IO-Link master module.
- Up to four standard sensors (2-wire/3-wire connection) can be connected.
- The 4SI IO-Link electronic module has a width of 15 mm and can be used with the following universal terminal modules:
  - TM-E15S26-A1 (screw terminals)
  - TM-E15C26-A1 (spring-type terminals)
  - TM-E15N26-A1 (FastConnect)
- Supports firmware update (STEP 7 V5.4 SP4 and higher).
- Corresponds to IO-Link Specification V1.0

Selection and ordering data

<table>
<thead>
<tr>
<th>Version</th>
<th>Connection</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>IO-Link 4SI electronic module</td>
<td>Screw terminals, spring-type terminals or FastConnect, depending on universal terminal module</td>
<td>6ES7138-4GA50-0AB0</td>
</tr>
</tbody>
</table>

6ES7138-4GA50-0AB0

Accessories

<table>
<thead>
<tr>
<th>Version</th>
<th>Connection</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Universal terminal modules for ET 200S Module type</td>
<td>Screw terminals</td>
<td>6ES7193-4CA40-0AA0</td>
</tr>
<tr>
<td>• TM-E15S26-A1</td>
<td>Spring-type terminals</td>
<td>6ES7193-4CA50-0AA0</td>
</tr>
<tr>
<td>• TM-E15C26-A1</td>
<td>FastConnect</td>
<td>6ES7193-4CA80-0AA0</td>
</tr>
<tr>
<td>• TM-E15N26-A1</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

More information

Manuals


Industry Mall

More information and technical specifications see Industry Mall under “Automation” ⇒ “Industrial Communication” ⇒ “IO-Link” ⇒ “Masters” ⇒ “IO-Link Master Modules for ET 200S”.

Overview

The SIRIUS 4SI electronic module allows the simple and cost-effective connection of SIRIUS devices with IO-Link to the multi-functional, distributed I/O system SIMATIC ET 200S at a total of four ports.

Features

- Up to 4 SIRIUS devices can be connected at the 4 ports of the SIRIUS 4SI electronic module. 3RA6 compact starters or load feeders with 3RA27 function modules can even be bundled in groups of four devices on one IO-Link port. It is possible therefore to connect up to 16 load feeders to the control system at one IO-Link master module.
- The SIRIUS 4SI electronic module has a width of 15 mm and can be used with the following universal terminal modules:
  - TM-E15S26-A1 (screw terminals)
  - TM-E15C26-A1 (spring-type terminals)
  - TM-E15N26-A1 (FastConnect)
- Supports firmware update (STEP 7 V5.4 SP5 and higher)
- Corresponds to IO-Link Specification V1.0

Selection and ordering data

<table>
<thead>
<tr>
<th>Version</th>
<th>Connection</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>SIRIUS 4SI electronic modules</td>
<td>Screw terminals, spring-type terminals or FastConnect, depending on universal terminal module</td>
<td>3RK1005-0LB00-0AA0</td>
</tr>
</tbody>
</table>

Accessories

<table>
<thead>
<tr>
<th>Version</th>
<th>Connection</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Universal terminal modules for ET 200S</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Module type</td>
<td></td>
<td>6ES7193-4CA0-0AA0</td>
</tr>
<tr>
<td>• TM-E15S26-A1</td>
<td>Screw terminals</td>
<td>6ES7193-4CA50-0AA0</td>
</tr>
<tr>
<td>• TM-E15C26-A1</td>
<td>Spring-type terminals</td>
<td>6ES7193-4CA80-0AA0</td>
</tr>
<tr>
<td>• TM-E15N26-A1</td>
<td>FastConnect</td>
<td></td>
</tr>
</tbody>
</table>

More information

Manuals

Industry Mall
More information and technical specifications see Industry Mall under “Automation” ⇒ “Industrial Communication” ⇒ “IO-Link” ⇒ “Masters” ⇒ “IO-Link Master Modules for ET 200S”.

SIIRIUS 4SI electronic modules for ET 200S
IO-Link
Masters

IO-Link master modules for ET 200eco PN

Overview

The ET 200eco PN IO-Link master module is an IO-Link master and enables easy connection of sensors and actuators from different manufacturers to the I/Os directly in the machine’s field area.

Features

- Up to four IO-Link devices (3-wire connection) can be connected to each IO-Link master module.
- Up to eight standard sensors (8 DI) and up to four standard actuators (4 DO) can be connected in addition.

Selection and ordering data

<table>
<thead>
<tr>
<th>Version</th>
<th>Connection</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>IO-Link master modules for ET 200eco PN Block I/Os in IP65</td>
<td>M12</td>
<td>6ES7148-6JA00-0AB0</td>
</tr>
</tbody>
</table>

More information

Manuals


Industry Mall

More information and technical specifications see Industry Mall under “Automation” ➞ “Industrial Communication” ➞ “IO-Link” ➞ “Masters” ➞ “IO-Link Master Modules for ET 200eco PN”.
Using IO-Link technology, it is basically possible to connect standard sensors to IO-Link masters. However, connecting standard sensors directly to the IO-Link master does not exploit the full potential of IO-Link. The solution lies in the technology of the IO-Link modules. Their use is a more economically attractive solution in comparison with the direct connection of a sensor.

IO-Link input modules are a sensible addition to the ET 200S distributed peripherals. The IO-Link input module technology enhances IO-Link via a pure point-to-point cable connection towards decentralized structures. The maximum cable length of an IO-Link connection between an IO-Link module and an IO-Link master is 20 m. The use of sensor boxes with accordingly complex and error-prone wiring is no longer necessary.

**Transmission of parameter and diagnostic signals**

The IO-Link input modules also offer the possibility of transmitting parameters and diagnostic signals. This enables for example the inputs of modules to be parameterized as NC contacts or NO contacts through IO-Link. An overload or short circuit in the sensor supply is signaled to the control system through the IO-Link master.

**M8 and M12 terminals**

M8 and M12 terminals are available for connecting the sensors. Connection to the IO-Link master is made using a standard M12 connecting cable.

**Benefits**

The use of IO-Link input modules has the following benefits:

- Economical use of innovative IO-Link technology also for binary sensors
- Optimum use of all ports of the IO-Link master
- Connection of several binary sensors/actuators to one port of the IO-Link master, hence low-cost connection of also binary sensors/actuators to the control system through IO-Link
- Reduction of digital input modules in the peripheral station
- Use of parameters also for binary sensors (e.g. NC contacts, NO contacts and input delay can be parameterized)
- Reduction of cabling and hence less risk of wiring errors by dispensing with sensor boxes
- Expansion toward distributed structures using pure point-to-point wiring
- Easy and elegant integration of sensors within a radius of 20 m around an ET 200S station
- Possibility of transmitting parameter and diagnostic signals (e.g. sensor supply overload)
- Can also be used in harsh ambient conditions thanks to the very compact design and degree of protection IP67

**Application**

IO-Link input modules are particularly used where sensor boxes had previously been used for the connection of binary sensors.

---

**Overview**

![IO-Link input modules](image)

**Benefits**

- Economical use of innovative IO-Link technology also for binary sensors
- Optimum use of all ports of the IO-Link master
- Connection of several binary sensors/actuators to one port of the IO-Link master, hence low-cost connection of also binary sensors/actuators to the control system through IO-Link
- Reduction of digital input modules in the peripheral station
- Use of parameters also for binary sensors (e.g. NC contacts, NO contacts and input delay can be parameterized)
- Reduction of cabling and hence less risk of wiring errors by dispensing with sensor boxes
- Expansion toward distributed structures using pure point-to-point wiring
- Easy and elegant integration of sensors within a radius of 20 m around an ET 200S station
- Possibility of transmitting parameter and diagnostic signals (e.g. sensor supply overload)
- Can also be used in harsh ambient conditions thanks to the very compact design and degree of protection IP67

**Application**

IO-Link input modules are particularly used where sensor boxes had previously been used for the connection of binary sensors.

---

**Overview**

Using IO-Link technology, it is basically possible to connect standard sensors to IO-Link masters. However, connecting standard sensors directly to the IO-Link master does not exploit the full potential of IO-Link. The solution lies in the technology of the IO-Link modules. Their use is a more economically attractive solution in comparison with the direct connection of a sensor.

IO-Link input modules are a sensible addition to the ET 200S distributed peripherals. The IO-Link input module technology enhances IO-Link via a pure point-to-point cable connection towards decentralized structures. The maximum cable length of an IO-Link connection between an IO-Link module and an IO-Link master is 20 m. The use of sensor boxes with accordingly complex and error-prone wiring is no longer necessary.

**Transmission of parameter and diagnostic signals**

The IO-Link input modules also offer the possibility of transmitting parameters and diagnostic signals. This enables for example the inputs of modules to be parameterized as NC contacts or NO contacts through IO-Link. An overload or short circuit in the sensor supply is signaled to the control system through the IO-Link master.

**M8 and M12 terminals**

M8 and M12 terminals are available for connecting the sensors. Connection to the IO-Link master is made using a standard M12 connecting cable.

**Benefits**

The use of IO-Link input modules has the following benefits:

- Economical use of innovative IO-Link technology also for binary sensors
- Optimum use of all ports of the IO-Link master
- Connection of several binary sensors/actuators to one port of the IO-Link master, hence low-cost connection of also binary sensors/actuators to the control system through IO-Link
- Reduction of digital input modules in the peripheral station
- Use of parameters also for binary sensors (e.g. NC contacts, NO contacts and input delay can be parameterized)
- Reduction of cabling and hence less risk of wiring errors by dispensing with sensor boxes
- Expansion toward distributed structures using pure point-to-point wiring
- Easy and elegant integration of sensors within a radius of 20 m around an ET 200S station
- Possibility of transmitting parameter and diagnostic signals (e.g. sensor supply overload)
- Can also be used in harsh ambient conditions thanks to the very compact design and degree of protection IP67

**Application**

IO-Link input modules are particularly used where sensor boxes had previously been used for the connection of binary sensors.

---

**Overview**

Using IO-Link technology, it is basically possible to connect standard sensors to IO-Link masters. However, connecting standard sensors directly to the IO-Link master does not exploit the full potential of IO-Link. The solution lies in the technology of the IO-Link modules. Their use is a more economically attractive solution in comparison with the direct connection of a sensor.

IO-Link input modules are a sensible addition to the ET 200S distributed peripherals. The IO-Link input module technology enhances IO-Link via a pure point-to-point cable connection towards decentralized structures. The maximum cable length of an IO-Link connection between an IO-Link module and an IO-Link master is 20 m. The use of sensor boxes with accordingly complex and error-prone wiring is no longer necessary.

**Transmission of parameter and diagnostic signals**

The IO-Link input modules also offer the possibility of transmitting parameters and diagnostic signals. This enables for example the inputs of modules to be parameterized as NC contacts or NO contacts through IO-Link. An overload or short circuit in the sensor supply is signaled to the control system through the IO-Link master.

**M8 and M12 terminals**

M8 and M12 terminals are available for connecting the sensors. Connection to the IO-Link master is made using a standard M12 connecting cable.

**Benefits**

The use of IO-Link input modules has the following benefits:

- Economical use of innovative IO-Link technology also for binary sensors
- Optimum use of all ports of the IO-Link master
- Connection of several binary sensors/actuators to one port of the IO-Link master, hence low-cost connection of also binary sensors/actuators to the control system through IO-Link
- Reduction of digital input modules in the peripheral station
- Use of parameters also for binary sensors (e.g. NC contacts, NO contacts and input delay can be parameterized)
- Reduction of cabling and hence less risk of wiring errors by dispensing with sensor boxes
- Expansion toward distributed structures using pure point-to-point wiring
- Easy and elegant integration of sensors within a radius of 20 m around an ET 200S station
- Possibility of transmitting parameter and diagnostic signals (e.g. sensor supply overload)
- Can also be used in harsh ambient conditions thanks to the very compact design and degree of protection IP67

**Application**

IO-Link input modules are particularly used where sensor boxes had previously been used for the connection of binary sensors.
## IO-Link

### Input modules

#### IO-Link K20 modules

### Selection and ordering data

<table>
<thead>
<tr>
<th>Type</th>
<th>Pin assignment</th>
<th>Connection</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>IO-Link K20 modules</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>• 4 inputs</td>
<td>Y</td>
<td>M12</td>
<td>3RK5010-0BA10-0AA0</td>
</tr>
<tr>
<td>• 8 inputs</td>
<td>Standard</td>
<td>M8</td>
<td>3RK5010-0CA00-0AA0</td>
</tr>
</tbody>
</table>

3RK5010-0BA10-0AA0

3RK5010-0CA00-0AA0
### Accessories

<table>
<thead>
<tr>
<th>Type</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>M12 sealing caps</strong> For free M12 sockets</td>
<td>3RK1901-1KA00</td>
</tr>
<tr>
<td><strong>M8 sealing caps</strong> For free M8 sockets</td>
<td>3RK1901-1PN00</td>
</tr>
<tr>
<td><strong>Control cables, assembled at one end</strong></td>
<td></td>
</tr>
<tr>
<td>Angular M12 socket for screw fixing, 4-pole, 4 x 0.34 mm², A-coded, black PUR sheath, max. 4 A</td>
<td>3RK1902-4GB50-4AA0</td>
</tr>
<tr>
<td><strong>Angular M12 socket</strong> for screw fixing, 4-pole screw terminals, max. 0.75 mm², A-coded, max. 4 A</td>
<td>3RK1902-4CA00-4AA0</td>
</tr>
<tr>
<td><strong>M12 plugs, straight</strong> For screw fixing, 5-pole screw terminals, max. 0.75 mm², A-coded, max. 4 A</td>
<td>3RK1902-4BA00-5AA0</td>
</tr>
<tr>
<td><strong>M12 plugs, angled</strong> For screw fixing, 5-pole screw terminals, max. 0.75 mm², A-coded, max. 4 A</td>
<td>3RK1902-4DA00-5AA0</td>
</tr>
<tr>
<td><strong>Control cables, assembled at one end</strong></td>
<td></td>
</tr>
<tr>
<td>M12 plugs, angled, for screw fixing, 5-pole, 5 x 0.34 mm², A-coded, black PUR sheath, max. 4 A</td>
<td>3RK1902-4HB15-5AA0, 3RK1902-4HB50-5AA0, 3RK1902-4HC01-5AA0</td>
</tr>
<tr>
<td><strong>Control cable, assembled at both ends</strong></td>
<td></td>
</tr>
<tr>
<td>Straight M12 plug, straight M12 socket, for screw fixing, 3-pole, 3 x 0.34 mm², A-coded, black PUR sheath, max. 4 A</td>
<td>3RK1902-4PB15-3AA0</td>
</tr>
<tr>
<td><strong>M12 Y-shaped coupler plugs</strong> For connection of two sensors to one M12 socket with Y assignment</td>
<td>6ES7194-1KA01-0XA0</td>
</tr>
</tbody>
</table>

### More information

**Industry Mall**

More information and technical specifications
see Industry Mall under "Automation"
⇒ "Industrial Communication" ⇒ "IO-Link" ⇒ "Input Modules"
⇒ "IO-Link K20 Modules".
Overview

**Contactors with communication interface, sizes S00 and S0**

Contactor versions with communication interface are required to establish a connection to the control system via IO-Link or AS-Interface. The link is established by means of function modules mounted on the front of the contactor.

**Standards**

IEC 60947-1, EN 60947-1, IEC 60947-4-1, EN 60947-4-1, IEC 60947-5-1, EN 60947-5-1 (auxiliary switches)

The 3RT2 contactors for switching motors are climate-proof and are suitable and tested for use worldwide.

If the devices are used in ambient conditions which deviate from common industrial conditions (IEC 60721-3-3 "Stationary Use, Weather-Protected"), information must be obtained about possible restrictions with regard to the reliability and endurance of the device and possible protective measures. In this case contact our Technical Assistance.

3RT2 contactors are finger-safe according to EN 50274.

The contactors are suitable for screw fixing or for mounting onto TH 35 standard mounting rails according to IEC 60715.

**Contact reliability**

If voltages $\leq 110$ V and currents $\leq 100$ mA are to be switched, the auxiliary contacts of the 3RT2 contactor or 3RH21 contactor relay should be used as they guarantee a high level of contact reliability.

These auxiliary contacts are suitable for solid-state circuits with currents $\geq 1$ mA at a voltage $\geq 17$ V.

**Connection methods**

The 3RT2 contactors are available with screw terminals or spring-type terminals.

**Short-circuit protection of the contactors**

Short-circuit protection of the contactors without overload relay, see "Technical specifications" (see Note).

To assemble fuseless motor feeders you must select combinations of motor starter protector and contactor as explained in "3RA2 Load Feeders".

**Motor protection**

3RU21 thermal overload relays or 3RB30 solid-state overload relays can be fitted to the 3RT2 contactors for protection against overload. The overload relays must be ordered separately.

**Ratings of three-phase motors**

The quoted rating (in kW) refers to the output power on the motor shaft (according to the nameplate).

**Control supply voltage**

Contactors with communication interface are available with 24 V DC operation.

**Manuals and configurator**

For more information, see

- System manual "SIRIUS Innovations – System Overview",

- Manual "SIRIUS Innovations – SIRIUS 3RT2 Contactors/ Contactor Assemblies",

For online configurator see

### Selection and ordering data

**DC operation · DC solenoid system**

*Rated control supply voltage 24 V*

<table>
<thead>
<tr>
<th>Rated data</th>
<th>Auxiliary contacts</th>
<th>Screw terminals</th>
<th>Spring-type terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td>AC-2 and AC-3, $T_u$: Up to 60 °C</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Operational current $I_u$ up to 400 V</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>400 V</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>A</td>
<td>kW</td>
<td>NO</td>
<td>NC</td>
</tr>
</tbody>
</table>

**For screw and snap-on mounting onto TH 35 standard mounting rail**

**Size S00**

**Contactors with communication interface**

Terminal designations in accordance with DIN EN 50012 or DIN EN 50005

- With auxiliary contact 1 NO, Ident. No. 10
- With auxiliary contact 1 NC, Ident. No. 01

<table>
<thead>
<tr>
<th>Article No.</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>3RT2015-1BB41-0CC0</td>
<td>3RT2015-2BB41-0CC0</td>
</tr>
<tr>
<td>3RT2016-1BB41-0CC0</td>
<td>3RT2016-2BB41-0CC0</td>
</tr>
<tr>
<td>3RT2017-1BB41-0CC0</td>
<td>3RT2017-2BB41-0CC0</td>
</tr>
<tr>
<td>3RT2018-1BB41-0CC0</td>
<td>3RT2018-2BB41-0CC0</td>
</tr>
</tbody>
</table>

**Size S0**

**Contactors with communication interface**

Terminal designations according to EN 50012

<table>
<thead>
<tr>
<th>Article No.</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>3RT2023-1BB40-0CC0</td>
<td>3RT2023-2BB40-0CC0</td>
</tr>
<tr>
<td>3RT2024-1BB40-0CC0</td>
<td>3RT2024-2BB40-0CC0</td>
</tr>
<tr>
<td>3RT2025-1BB40-0CC0</td>
<td>3RT2025-2BB40-0CC0</td>
</tr>
<tr>
<td>3RT2026-1BB40-0CC0</td>
<td>3RT2026-2BB40-0CC0</td>
</tr>
<tr>
<td>3RT2027-1BB40-0CC0</td>
<td>3RT2027-2BB40-0CC0</td>
</tr>
<tr>
<td>3RT2028-1BB40-0CC0</td>
<td>3RT2028-2BB40-0CC0</td>
</tr>
</tbody>
</table>

© Siemens AG 2014

1) Guide value for 4-pole standard motors at 50 Hz 400 V AC.

The actual starting and rated data of the motor to be switched must be considered when selecting the units.
IO-Link
Contactors and contactor assemblies

SIRIUS 3RA23 reversing contactor assemblies

Overview
The 3RA23 contactor assemblies for reversing can be ordered as follows:
- Complete, fully wired and tested, with mechanical and electrical interlock
- As individual parts for customer assembly.

The functions modules for establishing the connection to the control system must be separately ordered in both cases.

The auxiliary contacts integrated in the contactors (see page 5/19) can be freely assigned when function modules are used.

Selection and ordering data

Fully-wired and tested contactor assemblies

For online configurator see www.siemens.com/sirius/configurators.

1) Guide value for 4-pole standard motors at 50 Hz 400 V AC. The actual starting and rated data of the motor to be switched must be considered when selecting the units.

DC operation 24 V

<table>
<thead>
<tr>
<th>Size S00</th>
<th>With communication interface</th>
<th>Article No.</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>7</td>
<td>2.2</td>
<td>3RA2315-8XE30-1BB4</td>
<td>3RA2315-8XE30-2BB4</td>
</tr>
<tr>
<td>9</td>
<td>3</td>
<td>3RA2316-8XE30-1BB4</td>
<td>3RA2316-8XE30-2BB4</td>
</tr>
<tr>
<td>12</td>
<td>3</td>
<td>3RA2317-8XE30-1BB4</td>
<td>3RA2317-8XE30-2BB4</td>
</tr>
<tr>
<td>16</td>
<td>4</td>
<td>3RA2318-8XE30-1BB4</td>
<td>3RA2318-8XE30-2BB4</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Size S0</th>
<th>With communication interface</th>
<th>Article No.</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>12</td>
<td>3</td>
<td>3RA2324-8XE30-1BB4</td>
<td>3RA2324-8XE30-2BB4</td>
</tr>
<tr>
<td>16</td>
<td>4</td>
<td>3RA2325-8XE30-1BB4</td>
<td>3RA2325-8XE30-2BB4</td>
</tr>
<tr>
<td>25</td>
<td>5.5</td>
<td>3RA2326-8XE30-1BB4</td>
<td>3RA2326-8XE30-2BB4</td>
</tr>
<tr>
<td>32</td>
<td>7.5</td>
<td>3RA2327-8XE30-1BB4</td>
<td>3RA2327-8XE30-2BB4</td>
</tr>
<tr>
<td>38</td>
<td>7.5</td>
<td>3RA2328-8XE30-1BB4</td>
<td>3RA2328-8XE30-2BB4</td>
</tr>
</tbody>
</table>

© Siemens AG 2014
Components for customer assembly

Assembly kits for all sizes are available for customer assembly of reversing contactor assemblies.

Contactors, overload relays and function modules for reversing starting must be ordered separately.

Selection of contactors for customer assembly

<table>
<thead>
<tr>
<th>Rated data AC-2 and AC-3 for 50 Hz 400 V AC</th>
<th>Size</th>
<th>Article No. Contactor</th>
<th>Assembly kit</th>
<th>Complete assemblies</th>
</tr>
</thead>
<tbody>
<tr>
<td>kW</td>
<td>Operational current $I_e$ A</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3</td>
<td>7</td>
<td>S00</td>
<td>3RT2015- BB4-0CC0</td>
<td>3RA2913-2AA.</td>
</tr>
<tr>
<td>4</td>
<td>9</td>
<td>3RT2016- BB4-0CC0</td>
<td>3RA2316-8XB30- BB4</td>
<td></td>
</tr>
<tr>
<td>5.5</td>
<td>12</td>
<td>3RT2017- BB4-0CC0</td>
<td>3RA2317-8XB30- BB4</td>
<td></td>
</tr>
<tr>
<td>7.5</td>
<td>16</td>
<td>3RT2018- BB4-0CC0</td>
<td>3RA2318-8XB30- BB4</td>
<td></td>
</tr>
<tr>
<td>5.5</td>
<td>12</td>
<td>S0</td>
<td>3RT2024- BB40-0CC0</td>
<td>3RA2923-2AA.</td>
</tr>
<tr>
<td>7.5</td>
<td>16</td>
<td>3RT2025- BB40-0CC0</td>
<td>3RA2325-8XB30- BB4</td>
<td></td>
</tr>
<tr>
<td>11</td>
<td>25</td>
<td>3RT2026- BB40-0CC0</td>
<td>3RA2326-8XB30- BB4</td>
<td></td>
</tr>
<tr>
<td>15</td>
<td>32</td>
<td>3RT2027- BB40-0CC0</td>
<td>3RA2327-8XB30- BB4</td>
<td></td>
</tr>
<tr>
<td>18.5</td>
<td>38</td>
<td>3RT2028- BB40-0CC0</td>
<td>3RA2328-8XB30- BB4</td>
<td></td>
</tr>
</tbody>
</table>

Assembly kits for making 3-pole contactor assemblies

<table>
<thead>
<tr>
<th>Type</th>
<th>For contactors</th>
<th>Size</th>
<th>Version</th>
<th>Screw terminals</th>
<th>Spring-type terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td>3RT201</td>
<td>S00-S00</td>
<td>The assembly kit contains: Mechanical interlock, 2 connecting clips for 2 contactors, wiring modules on the top and bottom • For main, auxiliary and control circuits</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>3RT202</td>
<td>S0-S0</td>
<td>The assembly kit contains: Mechanical interlock, 2 connecting clips for 2 contactors, wiring modules on the top and bottom • For main, auxiliary and control circuits • Only for main circuit</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1) Version in size S0 with spring-type terminals:
   Only the wiring modules for the main circuit are included.
   No connectors are included for the auxiliary and control circuit.
Overview

These 3RA24 contactor assemblies for wye-delta starting are designed for standard applications.

Note:
Contactor assemblies for wye-delta starting in special applications such as very heavy starting or wye-delta starting of special motors must be customized. Help with designing such special applications is available from Technical Assistance.

The 3RA24 contactor assemblies for wye-delta starting can be ordered as follows:
- Complete, fully wired and tested, with electrical and mechanical interlock
- As individual parts for customer assembly.

A dead interval of 50 ms on reversing is already integrated in the function module for wye-delta starting. The auxiliary contacts integrated in the contactors (see page 5/19) are unassigned.

Selection and ordering data

Fully-wired and tested contactor assemblies

<table>
<thead>
<tr>
<th>Article No.</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>3RA2415-8XE31-1BB4</td>
<td>3RA2416-8XE31-1BB4</td>
</tr>
<tr>
<td>3RA2416-8XE31-1BB4</td>
<td>3RA2416-8XE31-2BB4</td>
</tr>
<tr>
<td>3RA2417-8XE31-1BB4</td>
<td>3RA2417-8XE31-2BB4</td>
</tr>
<tr>
<td>3RA2423-8XE32-1BB4</td>
<td>3RA2423-8XE32-2BB4</td>
</tr>
<tr>
<td>3RA2425-8XE32-1BB4</td>
<td>3RA2425-8XE32-2BB4</td>
</tr>
<tr>
<td>3RA2426-8XE32-1BB4</td>
<td>3RA2426-8XE32-2BB4</td>
</tr>
</tbody>
</table>

DC operation 24 V

Size S00

For IO-Link connection

| Size | Operational current Ie up to 400 V | Ratings of three-phase motors1) at 50 Hz and | Rated control supply voltage Ues | Screw terminals | Spring-type terminals | Article No. | Article No. |
|------|-----------------------------------|--------------------------------------------|-------------------------------|----------------|-----------------------|-------------|
| 12   | 3.3                               | 5.5                                       | 7.2                           | 9.2            | 24 DC                 | 3RA2415-8XE31-1BB4 | 3RA2415-8XE31-2BB4 |
| 16   | 4.7                               | 7.5                                       | 10.3                          | 9.2            | 24 DC                 | 3RA2416-8XE31-1BB4 | 3RA2416-8XE31-2BB4 |
| 25   | 5.5                               | 11                                        | 11                            | 24 DC          |                       | 3RA2417-8XE31-1BB4 | 3RA2417-8XE31-2BB4 |

Size S50

For IO-Link connection

| Size | Operational current Ie up to 400 V | Ratings of three-phase motors1) at 50 Hz and | Rated control supply voltage Ues | Screw terminals | Spring-type terminals | Article No. | Article No. |
|------|-----------------------------------|--------------------------------------------|-------------------------------|----------------|-----------------------|-------------|
| 25   | 7.1                               | 11                                        | 15.6                          | 19             | 24 DC                 | 3RA2423-8XE32-1BB4 | 3RA2423-8XE32-2BB4 |
| 32 / 40 | 11.4                          | 15 / 18.5                                 | 19                            | 19             | 24 DC                 | 3RA2425-8XE32-1BB4 | 3RA2425-8XE32-2BB4 |
| 50   | --                                | 22                                        | 19                            | 19             | 24 DC                 | 3RA2426-8XE32-1BB4 | 3RA2426-8XE32-2BB4 |

1) Guide value for 4-pole standard motors at 50 Hz 400 V AC.

The actual starting and rated data of the motor to be switched must be considered when selecting the units.
Components for customer assembly

Assembly kits with wiring modules and mechanical connectors are available for contactor assemblies for wye-delta starting. Contactors, overload relays, function modules for wye-delta starting, auxiliary switches for electrical interlock – if required also infeed terminals – must be ordered separately.

Selection of contactors for customer assembly

<table>
<thead>
<tr>
<th>Rated data AC-3 at 50 Hz 400 V AC</th>
<th>Operational current $I_e$ A</th>
<th>Motor current A</th>
<th>Size</th>
<th>Article No. Line/delta contactor</th>
<th>Star contactor</th>
<th>Complete assemblies</th>
</tr>
</thead>
<tbody>
<tr>
<td>kW</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>5.5</td>
<td>12</td>
<td>9.5 ... 13.8</td>
<td>S00-S00-S00</td>
<td>3RT2015-.BB4.-0CC0</td>
<td>3RT2015-.BB4.-0CC0</td>
<td>3RA2415-8XE31-.BB4</td>
</tr>
<tr>
<td>7.5</td>
<td>16</td>
<td>12.1 ... 17</td>
<td>S00-S00-S00</td>
<td>3RT2017-.BB4.-0CC0</td>
<td>3RT2017-.BB4.-0CC0</td>
<td>3RA2416-8XE31-.BB4</td>
</tr>
<tr>
<td>11</td>
<td>25</td>
<td>19 ... 25</td>
<td>S00-S00</td>
<td>3RT2024-.BB40-0CC0</td>
<td>3RT2024-.BB40-0CC0</td>
<td>3RA2423-8XE32-.BB4</td>
</tr>
<tr>
<td>15</td>
<td>32</td>
<td>24.1 ... 34</td>
<td>S00-S00</td>
<td>3RT2026-.BB40-0CC0</td>
<td>3RT2026-.BB40-0CC0</td>
<td>3RA2425-8XE32-.BB4</td>
</tr>
<tr>
<td>18.5</td>
<td>40</td>
<td>34.5 ... 40</td>
<td>S00-S00</td>
<td>3RT2026-.BB40-0CC0</td>
<td>3RT2026-.BB40-0CC0</td>
<td>3RA2425-8XE32-.BB4</td>
</tr>
<tr>
<td>22</td>
<td>50</td>
<td>31 ... 43</td>
<td>S00-S00</td>
<td>3RT2027-.BB40-0CC0</td>
<td>3RT2027-.BB40-0CC0</td>
<td>3RA2426-8XE32-.BB4</td>
</tr>
</tbody>
</table>

For contactors, see page 5/19.

Assembly kits for making 3-pole contactor assemblies

<table>
<thead>
<tr>
<th>Type</th>
<th>Article No. Screw terminals Article No. Spring-type terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td>3RT201 S00</td>
<td>3RA2913-2BB1</td>
</tr>
<tr>
<td>3RT202 S0</td>
<td>3RA2923-2BB1</td>
</tr>
</tbody>
</table>

1) When using the function modules for wye-delta starting, the wiring modules included in the assembly kit for the auxiliary current are not required.

2) Version in size S0 with spring-type terminals: Only the wiring modules for the main circuit are included. No connectors are included for the auxiliary and control circuit.
### Overview

The function modules for mounting onto contactors enable the configuration of starters and contactor assemblies for direct-on-line, reversing and wye-delta starting without any additional, complicated wiring of the individual components.

They include the key control functions required for the particular feeder, e.g. timing and interlocking, and can be connected to the control system via IO-Link.

### Selection and ordering data

<table>
<thead>
<tr>
<th>Version</th>
<th>Screw terminals</th>
<th>Spring-type terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>Article No.</td>
<td>Article No.</td>
</tr>
<tr>
<td><strong>Function modules for direct-on-line starting</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td><img src="image1.jpg" alt="Image" /></td>
<td>3RA2711-1AA00</td>
<td>3RA2711-2AA00</td>
</tr>
<tr>
<td><img src="image2.jpg" alt="Image" /></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Function modules for reversing starting</strong></td>
<td>3RA2711-1BA00</td>
<td>3RA2711-2BA00</td>
</tr>
<tr>
<td><img src="image3.jpg" alt="Image" /></td>
<td>3RA2711-1BA00</td>
<td></td>
</tr>
<tr>
<td><img src="image4.jpg" alt="Image" /></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Function modules for wye-delta starting</strong></td>
<td>3RA2711-1CA00</td>
<td>3RA2711-2CA00</td>
</tr>
<tr>
<td><img src="image5.jpg" alt="Image" /></td>
<td>3RA2711-1CA00</td>
<td></td>
</tr>
<tr>
<td><img src="image6.jpg" alt="Image" /></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Suitable contactors or reversing contactor assemblies with communication interface are required (see pages 5/19 and 5/20).

**Note:**

When using the function modules, no other auxiliary switches are allowed to be connected to the basic units.

1) For prewired contactor assemblies for reversing starting with communication interface, see page 5/20. When these contactor assemblies are used, the assembly kit for the wiring is already integrated.

2) For complete contactor assemblies for wye-delta starting incl. function modules, see page 5/22.

**Manuals**

### Selection and ordering data (continued)

<table>
<thead>
<tr>
<th>Accessories</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Module connector set</strong>, comprising:</td>
<td></td>
</tr>
<tr>
<td>• 2 module connectors, 14-pole, short</td>
<td>3RA2711-0EE01</td>
</tr>
<tr>
<td>• 2 interface covers</td>
<td></td>
</tr>
<tr>
<td><strong>Module connectors</strong>, 14-pole, 8 cm</td>
<td>3RA2711-0EE02</td>
</tr>
<tr>
<td>For size jump S00-S0 + 1 space</td>
<td></td>
</tr>
<tr>
<td><strong>Module connectors</strong>, 14-pole, 21 cm</td>
<td>3RA2711-0EE03</td>
</tr>
<tr>
<td>For various space combinations</td>
<td></td>
</tr>
<tr>
<td><strong>Module connectors</strong>, 10-pole, 8 cm</td>
<td>3RA2711-0EE04</td>
</tr>
<tr>
<td>For separate auxiliary voltage infeed within an IO-Link group</td>
<td></td>
</tr>
<tr>
<td><strong>Sealable covers</strong></td>
<td>3RA2910-0</td>
</tr>
<tr>
<td>for 3RA27, 3RA28, 3RA29</td>
<td></td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Operator panels</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Operator panel (set)</strong>, comprising:</td>
<td>3RA6935-0A</td>
</tr>
<tr>
<td>• 1 x operator panel</td>
<td></td>
</tr>
<tr>
<td>• 1 x enabling module</td>
<td></td>
</tr>
<tr>
<td>• 1 x interface cover</td>
<td></td>
</tr>
<tr>
<td>• 1 x fixing terminal</td>
<td></td>
</tr>
<tr>
<td><strong>Connection cable</strong>, length 2 m, 10- to 14-pole</td>
<td>3RA2711-0EE11</td>
</tr>
<tr>
<td>For connecting the operator panel to the communication module</td>
<td></td>
</tr>
<tr>
<td><strong>Enabling modules (replacement)</strong></td>
<td>3RA6936-0A</td>
</tr>
<tr>
<td><strong>Interface covers (replacement)</strong></td>
<td>3RA6936-0B</td>
</tr>
</tbody>
</table>

1) Suitable only for communication through IO-Link.
### Overview

The modular 3RB24 solid-state overload relay, which is powered via IO-Link (with monostable auxiliary contacts) up to 630 A (up to 820 A possible with a series transformer) have been designed for inverse-time delayed protection of loads with normal and heavy starting ("Function" see Manual "SIRIUS 3RB24 Solid-State Overload Relay for IO-Link", [http://support.automation.siemens.com/WW/view/en/46165627](http://support.automation.siemens.com/WW/view/en/46165627)) against excessive temperature rises due to overload, phase unbalance or phase failure. It comprises an evaluation unit, a current measuring module and a connecting cable.

The 3RB24 evaluation module also offers a motor starter function. The contactors, which are connected via the auxiliary contacts, can also be actuated for operation via IO-Link. In this way, direct, reversing and star-delta starters up to 630 A (or 830 A) can be connected to the controller wirelessly via the IO-Link.

An overload, phase unbalance or phase failure result in an increase of the motor current beyond the set rated motor current. This current rise is detected by means of the current measuring module (see page 5/30) and electronically evaluated by the evaluation module which is connected to it. The evaluation electronics sends a signal to the auxiliary contacts. The auxiliary contacts then switch off the load by means of a contactor.

The break time depends on the ratio between the tripping current and current setting $I_n$ and is stored in the form of a long-term stable tripping characteristic (see “Characteristic Curves” [http://support.automation.siemens.com/WW/view/en/20357046/134300](http://support.automation.siemens.com/WW/view/en/20357046/134300)). The "trippled" status is signaled by means of a continuously illuminated red "OVERLOAD" LED and also reported as a group fault via IO-Link.

The LED indicates imminent tripping of the relay due to overload, phase unbalance or phase failure by flickering when the limit current has been violated. This warning can also be reported to the higher-level PLC via IO-Link at the 3RB24 overload relay.

In addition to the described inverse-time delayed protection of loads against excessive temperature rises, the 3RB24 solid-state overload relays also allow direct temperature monitoring of the motor windings (full motor protection) by connection with broken-wire interlock of a PTC sensor circuit. With this temperature-dependent protection, the loads can be protected against overheating caused indirectly by reduced coolant flow, for example, which cannot be detected by means of the current alone.

In the event of overtemperature, the devices switch off the contactor, and thus the load, by means of the auxiliary contacts. The "trippled" status is signaled by means of a continuously illuminated "THERMIS" LED and also reported as a group fault via IO-Link.

To protect the loads against incomplete ground faults due to damage to the insulation, humidity, condensed water, etc., the 3RB24 solid-state overload relays offer the possibility of internal ground-fault detection (for details, see Manual "SIRIUS 3RB24 Solid-State Overload Relay for IO-Link", [http://support.automation.siemens.com/WW/view/en/46165627](http://support.automation.siemens.com/WW/view/en/46165627), not possible in conjunction with contactor assemblies for wye-delta starting). In the event of a ground fault, the 3RB24 relays trip instantaneously.

The "trippled" status is signaled by means of a flashing red LED "Ground Fault" and reported at the 3RB24 overload relay as a group fault via IO-Link.

The reset after overload, phase unbalance, phase failure, thermostat or ground-fault tripping is performed manually by key on site, via IO-Link or by electrical remote RESET or automatically after the cooling time (motor model) or for thermostat protection after sufficient cooling. Power cuts in devices due to function monitors (broken wire or short-circuit on the thermostat) can only be reset on-site (“Function” see Manual "SIRIUS 3RB24 Solid-State Overload Relay for IO-Link", [http://support.automation.siemens.com/WW/view/en/46165627](http://support.automation.siemens.com/WW/view/en/46165627)).
Overview (continued)

In conjunction with a function expansion module, the motor current measured by the microprocessor can be output in the form of an analog signal DC 4 to 20 mA for operating rotary coil instruments or for feeding into analog inputs of programmable logic controllers.

The current values can be transmitted to the higher-level controller via IO-Link.


The devices are manufactured in accordance with environmental guidelines and contain environmentally friendly and reusable materials. They comply with all important worldwide standards and approvals.

Type of protection "increased safety EEx e and explosion-proof enclosure EEx d" in accordance with ATEX Directive 94/9/EC

The 3RB24 solid-state overload relay (monostable) are suitable for the overload protection of explosion-proof motors of types of protection EEx e and EEx d.

They comply with the requirements of IEC 60079-7 (Electrical devices for areas subject to explosion hazards - Increased safety "e" as well as for flameproof enclosure "d").

EC type test certificate for Group II, Category (2) G/D has been submitted. On request.

Connection methods

The evaluation modules of the 3RB24 solid-state overload relays for High-Feature applications are available with screw terminals (box terminals) or spring-type terminals at the auxiliary current end.

The 3RB29 current measuring modules are designed as straight-through modules. From size S6 upwards they are also available with an optional busbar connection.

Connection methods

Screw terminals

Spring-type terminals

The various terminals are indicated in the corresponding tables by the displayed symbols.

Overload relays overview – matching contactors

<table>
<thead>
<tr>
<th>Overload relays</th>
<th>Current measuring module</th>
<th>Current range</th>
<th>Contactors (type, size, rating in kW)</th>
</tr>
</thead>
<tbody>
<tr>
<td>Type</td>
<td>Type</td>
<td>A</td>
<td>3RT201. 3RT202. 3RT103. 3RT104. 3RT105. 3RT106. 3RT107. 3TF68/3TF69</td>
</tr>
<tr>
<td>3RB24</td>
<td></td>
<td></td>
<td>S00 3/4/5/7.5 S0 5.5/7.5/11 S2 15/18.5/22 S3 30/37/45 S6 55/75/90 S10 110/132/160 S12 200/250 S14 375/450</td>
</tr>
</tbody>
</table>

| 3RB2483 +      | 3RB2906                  | 0.3 … 25      | ✓ ✓ -- -- -- -- -- -- |
| 3RB2483 +      | 3RB2906                  | 10 … 100      | ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ |
| 3RB2483 +      | 3RB2906                  | 20 … 200      | ✓ ✓ ✓ ✓ ✓ ✓ ✓ ✓ |
| 3RB2483 +      | 3RB2906                  | 63 … 630      | -- -- -- -- -- -- -- -- |
| 3RB2483 +      | 3RB2906 + 3UF18          | 630 … 820     | -- -- -- -- -- -- -- -- |

✓ Can be used
-- Cannot be used

1) “Technical specifications” for the use of overload relays with trip class ≥ CLASS 20 can be found in “Short-circuit protection with fuses for motor feeders”, see Configuration Manuals

Benefits

The key features and benefits of the 3RB24 solid-state overload relays for IO-Link are listed in the overview table (see Catalog IC 10, Chapter 7 “Protection Equipment” → “Overload Relays” → “General Data”).

SIRIUS 3RB24 solid-state overload relays (continued)
IO-Link
SIRIUS 3RB24 solid-state overload relays for IO-Link

3RB24 for IO-Link, up to 630 A for High-Feature applications

Application

Industries
The 3RB24 solid-state overload relays are suitable for customers from all industries who want to guarantee optimum inverse-time delayed and temperature-dependent protection of their electrical loads (e.g., motors) under normal and heavy starting conditions (CLASS 5 to 30), minimize project completion times, inventories and energy consumption, and optimize plant availability and maintenance management.

Application area
The 3RB24 solid-state overload relays have been designed for the protection of three-phase asynchronous and single-phase AC motors.

In addition to protection function, these devices can be used together with contactors as direct or reversing starters (star-delta (wye-delta) start also possible), which are controlled via IO-Link. This makes it possible to directly control drives via IO-Link from a higher-level controller or on site via the optional hand-held device lamps and also, for example, to return current values directly via IO-Link.

If single-phase AC motors are to be protected by the 3RB24 solid-state overload relays, the main current paths of the current measuring modules must be series-connected (“Circuit Diagrams” see Manual “SIRIUS 3RB24 Solid-State Overload Relay for IO-Link”, http://support.automation.siemens.com/WW/view/en/46165627).

Ambient conditions
The devices are insensitive to external influences such as shocks, corrosive ambient conditions, ageing and temperature fluctuations.

For the temperature range from –25 °C to +60 °C, the 3RB24 solid-state overload relays compensate the temperature in accordance with IEC 60947-4-1.

Configuration notes for use of the devices below –25 °C or above +60 °C on request.
Selection and ordering data

3RB24 solid-state overload relays (evaluation modules) for full motor protection, stand-alone installation, CLASS 5, 10, 20 and 30, adjustable

<table>
<thead>
<tr>
<th>Features and technical specifications</th>
<th>3RB2483-4A.1</th>
</tr>
</thead>
<tbody>
<tr>
<td>Overload protection, phase failure protection and unbalance protection</td>
<td>✓</td>
</tr>
<tr>
<td>Supplied from an external voltage</td>
<td>✓ 24 V DC through IO-Link</td>
</tr>
<tr>
<td>Direct-on-line or reversing starters (wye-delta starting also possible) controllable through IO-Link</td>
<td>✓</td>
</tr>
<tr>
<td>Auxiliary contacts</td>
<td>✓ 1 CO and 1 NO in series</td>
</tr>
<tr>
<td>Manual and automatic RESET</td>
<td>✓</td>
</tr>
<tr>
<td>Remote-RESET</td>
<td>✓ (electrically or via IO-Link)</td>
</tr>
<tr>
<td>Four LEDs for operating and status displays</td>
<td>✓</td>
</tr>
<tr>
<td>TEST function and self-monitoring</td>
<td>✓</td>
</tr>
<tr>
<td>Internal ground-fault detection</td>
<td>✓</td>
</tr>
<tr>
<td>Screw or spring-type terminals for auxiliary, control and sensor circuits</td>
<td>✓</td>
</tr>
<tr>
<td>Input for PTC sensor circuit</td>
<td>✓</td>
</tr>
<tr>
<td>Analog output</td>
<td>✓</td>
</tr>
</tbody>
</table>

IO-Link-specific functions

- Connection of direct-on-line, reversing and star-delta starters to the controller via IO-Link ✓
- On-site controlling of the starter using the hand-held device ✓
- Accessing process data (e.g. current values in all three phases) via IO-Link ✓
- Accessing parameterization and diagnostics data (e.g. tripped signals) via IO-Link ✓

Available

PU (UNIT, SET, M) = 1
PS* = 1 unit
PG = 41G

Size contactor

<table>
<thead>
<tr>
<th>Evaluation modules</th>
</tr>
</thead>
<tbody>
<tr>
<td>S00 ... S12 Monostable</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Article No.</th>
<th>Screw terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td>3RB2483-4AA1</td>
<td>✓</td>
</tr>
<tr>
<td>3RB2483-4AC1</td>
<td>✓</td>
</tr>
</tbody>
</table>

Notes:

Overview of overload relays – matching contactors see page 5/27.

Analog input modules, e.g. SM 331, must be configured for 4-wire measuring transducers. The analog input module may not supply current to the analog output of the 3RB24 relay.

For current measuring modules and related connecting cables see next page, “Accessories” see pages 5/31 and 5/32.
IO-Link
SIRIUS 3RB24 solid-state overload relays for IO-Link

Current measuring modules

Overview

The current measuring modules are designed as system components for connecting to 3RB24 evaluation units. Using these evaluation units the motor current is measured and the measured value sent to the evaluation unit for evaluation.

The current measuring modules in sizes S00 to S3 up to 55 mm wide are equipped with straight-through transformers and can be snap-fitted under the evaluation units. The larger evaluation units are installed directly on the contactor or as stand-alone units.

Selection and ordering data

Current measuring modules for mounting onto contactor¹ and stand-alone installation¹ ² (essential accessories)

<table>
<thead>
<tr>
<th>Size contactor³</th>
<th>Rating for three-phase motor, rated value⁴</th>
<th>Current setting value of the inverse-time delayed overload release</th>
<th>Short-circuit protection with fuse, type of coordination &quot;2&quot;, operational class gG⁵</th>
<th>For overload relays</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sizes S00/S0¹ ²</td>
<td>S00/S0 0,09 ... 1,1 1,1 ... 11</td>
<td>0,3 ... 3 2,4 ... 25</td>
<td>20 63</td>
<td>3RB24</td>
<td>3RB2906-2BG1</td>
</tr>
<tr>
<td></td>
<td>S00/S0 0,3 ... 3 2,4 ... 25</td>
<td>20 63</td>
<td>3RB24</td>
<td>3RB2906-2DG1</td>
<td></td>
</tr>
<tr>
<td>3RB2906-2BG1, 3RB2906-2DG1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Sizes S2/S3¹ ²</td>
<td>S2/S3 5,5 ... 45 10 ... 100</td>
<td>315 315</td>
<td>3RB24</td>
<td>3RB2906-2JG1</td>
<td></td>
</tr>
<tr>
<td></td>
<td>S2/S3 5,5 ... 45 10 ... 100</td>
<td>315 315</td>
<td>3RB24</td>
<td>3RB2906-2JG1</td>
<td></td>
</tr>
<tr>
<td>3RB2906-2JG1</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Size S6¹ ²</td>
<td>S6 with busbar connection 11 ... 90</td>
<td>20 ... 200 315</td>
<td>3RB24</td>
<td>3RB2956-2TH2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>S6 with busbar connection 11 ... 90</td>
<td>20 ... 200 315</td>
<td>3RB24</td>
<td>3RB2956-2TH2</td>
<td></td>
</tr>
<tr>
<td>3RB2956-2TG2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Sizes S10/S12¹ ²</td>
<td>S10/S12 and size 14 (3TF68/ 3TF69) 37 ... 450 63 ... 630</td>
<td>800</td>
<td>3RB24</td>
<td>3RB2966-2WH2</td>
<td></td>
</tr>
<tr>
<td></td>
<td>S10/S12 and size 14 (3TF68/ 3TF69) 37 ... 450 63 ... 630</td>
<td>800</td>
<td>3RB24</td>
<td>3RB2966-2WH2</td>
<td></td>
</tr>
<tr>
<td>3RB2966-2WH2</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Note:
The connecting cable between the current measuring module and the evaluation module is not included in the scope of supply; please order separately.

¹ The current measuring modules with an Article No. ending with "2" are designed for mounting onto contactor and stand-alone installation. For 3TF68/3TF69 contactors, direct mounting is not possible.
² The current measuring modules with an Article No. ending with "1" are designed for stand-alone installation.
³ Observe maximum rated operational current of the devices.
⁴ Guide value for 4-pole standard motors at 50 Hz 400 V AC. The actual starting and rated data of the motor to be protected must be considered when selecting the units.
⁵ Maximum protection by fuse only for overload relay, type of coordination "2". For fuse values in connection with contactors see Configuration Manuals.
⁶ The modules with an Article No. with "G" in penultimate position are equipped with a straight-through transformer.

Accessories

<table>
<thead>
<tr>
<th>Size contactor</th>
<th>Version</th>
<th>For overload relays</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Connecting cables (necessary accessories)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>S00 ... S3</td>
<td>For connection between evaluation module and current measuring module</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3RB2987-2B</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>S00 ... S12</td>
<td>Length 0.1 m (only for mounting of the evaluation module directly onto the current measuring module)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>3RB2987-2D</td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Additional general accessories see page 5/32.
## Overview

**Overload relays for High-Feature applications**

The following optional accessories are available for the 3RB24 solid-state overload relays:

- Operator panel for the 3RB24 evaluation modules
- Manual for the 3RB24 evaluation modules
- Sealable covers for the 3RB24 evaluation modules
- Terminal covers for the 3RB29 current measuring modules size S6 and S10/S12
- Box terminal blocks for the 3RB29 current measuring modules size S6 and S10/S12
- Push-in lugs for screw fixing for 3RB24 evaluation modules and 3RB2906 current measuring modules

## Selection and ordering data

### Accessories for 3RB24 overload relays

<table>
<thead>
<tr>
<th>Version</th>
<th>For overload relays</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Operator panels for evaluation modules</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Operator panels (set)</td>
<td>3RB24</td>
<td>3RA6935-0A</td>
</tr>
<tr>
<td>One set comprises:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>- 1 x operator panel</td>
<td></td>
<td></td>
</tr>
<tr>
<td>- 1 x 3RA6936-0A enabling module</td>
<td></td>
<td></td>
</tr>
<tr>
<td>- 1 x 3RA6936-0B interface cover</td>
<td></td>
<td></td>
</tr>
<tr>
<td>- 1 x fixing terminal</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Note:</td>
<td></td>
<td></td>
</tr>
<tr>
<td>The connecting cable between the evaluation module and the operator panel is not included in the scope of supply; please order separately.</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Connecting cable</strong></td>
<td>3RB24</td>
<td>3UF7933-0BA00-0</td>
</tr>
<tr>
<td>Length 2.5 m (round),</td>
<td></td>
<td></td>
</tr>
<tr>
<td>for connecting the evaluation module to the operator panel</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Enabling modules (replacement)</strong></td>
<td>3RB24</td>
<td>3RA6936-0A</td>
</tr>
<tr>
<td><strong>Interface covers</strong></td>
<td>3RB24</td>
<td>3RA6936-0B</td>
</tr>
</tbody>
</table>

### Manuals

**Manual "Solid-State Overload Relay for IO-Link"**


**Manual "Solid-State Overload Relay for IO-Link"**

Additional general accessories see next page.
IO-Link
SIRIUS 3RB24 solid-state overload relays for IO-Link

Accessories

Selection and ordering data (continued)

**General accessories**

<table>
<thead>
<tr>
<th>Version</th>
<th>Size</th>
<th>For overload relays</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Sealable covers for evaluation modules</td>
<td>For covering the setting knobs</td>
<td>--</td>
<td>3RB24</td>
</tr>
<tr>
<td>Terminal covers for current measuring modules</td>
<td>Covers for cable lugs and busbar connections</td>
<td>Length 100 mm S6</td>
<td>3RB2956</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Length 120 mm S10/S12</td>
<td>3RB2966</td>
</tr>
<tr>
<td></td>
<td>Covers for box terminals</td>
<td>Length 25 mm S6</td>
<td>3RB2956</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Length 30 mm S10/S12</td>
<td>3RB2966</td>
</tr>
<tr>
<td></td>
<td>Covers for screw terminals</td>
<td>between contactor and overload relay, without box terminals (1 unit required per combination)</td>
<td>S6</td>
</tr>
<tr>
<td></td>
<td></td>
<td>S10/S12</td>
<td>3RB2966</td>
</tr>
<tr>
<td>Box terminal blocks for current measuring modules</td>
<td>For round and ribbon cables</td>
<td>Up to 70 mm² S6</td>
<td>3RB2956</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Up to 120 mm² S6</td>
<td>3RB2956</td>
</tr>
<tr>
<td></td>
<td></td>
<td>Up to 240 mm² S10/S12</td>
<td>3RB2966</td>
</tr>
<tr>
<td>Push-in lugs for evaluation modules and current measuring modules</td>
<td>For screw fixing the evaluation modules</td>
<td>--</td>
<td>3RP1903</td>
</tr>
<tr>
<td></td>
<td>For screw fixing the current measuring modules (2 units per module)</td>
<td>S00 ... S3</td>
<td>3RB1900-0B</td>
</tr>
</tbody>
</table>

**Tools for opening spring-type terminals**

<table>
<thead>
<tr>
<th>Version</th>
<th>Size</th>
<th>Color</th>
<th>For overload relays</th>
<th>Spring-type terminals Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Screwdrivers</td>
<td>For all SIRIUS devices with spring-type terminals</td>
<td>Length approx. 200 mm, 3.0 mm x 0.5 mm Titanium gray, black, partially insulated</td>
<td>Main and auxiliary circuit connection: 3RB24</td>
<td></td>
</tr>
<tr>
<td>Blank labels</td>
<td><strong>Unit labeling plates</strong>¹</td>
<td>20 mm x 7 mm Pastel turquoise</td>
<td>3RB24</td>
<td></td>
</tr>
<tr>
<td></td>
<td></td>
<td>20 mm x 7 mm Titanium gray</td>
<td>3RB24</td>
<td></td>
</tr>
</tbody>
</table>

¹ PC labeling system for individual inscription of unit labeling plates available from: murrplastik Systemtechnik GmbH (see Catalog IC 10, Chapter 16, "Appendix" ⇒ "External Partners").
Overview

Communications integration using IO-Link

The 3RA64/65 compact starters comply with IO-Link specification V1.0. Up to 4 compact starters in IO-Link version (reversing and direct-on-line starters) can be connected together and easily linked to the IO-Link master through a standardized IO-Link connection. The 4SI SIRIUS electronic module can be used, for example, as an IO-Link master for the connection to the SIMATIC ET 200S distributed I/O system.

The IO-Link connection enables a high density of information in the local range.

The diagnostics data of the process collected by the 3RA6 compact starter, e.g. short circuit, end of service life, limit position etc., are not only indicated on the compact starter itself but also transmitted to the higher-level control system through IO-Link.

Thanks to the optionally available operator panel, which can be installed in the control cabinet door, it is easy to control the 3RA6 compact starter with IO-Link from the control cabinet door.

Selection and ordering data

3RA64 direct-on-line starters

<table>
<thead>
<tr>
<th>Setting range for solid-state overload release</th>
<th>Instantaneous overcurrent release</th>
</tr>
</thead>
<tbody>
<tr>
<td>Screw terminals</td>
<td>Spring-type terminals</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>kW</th>
<th>A</th>
<th>A</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.09</td>
<td>0.1...0.4</td>
<td>56</td>
</tr>
<tr>
<td>0.37</td>
<td>0.32...1.25</td>
<td>56</td>
</tr>
<tr>
<td>1.5</td>
<td>1...4</td>
<td>56</td>
</tr>
<tr>
<td>5.5</td>
<td>3...12</td>
<td>168</td>
</tr>
<tr>
<td>15</td>
<td>8...32</td>
<td>448</td>
</tr>
</tbody>
</table>

For standard mounting rail or screw fixing, including 1 pair of main circuit terminals and 1 pair of control circuit terminals

<table>
<thead>
<tr>
<th>Article No.</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>3RA6400-1AB42</td>
<td>3RA6400-2AB42</td>
</tr>
<tr>
<td>3RA6400-1BB42</td>
<td>3RA6400-2BB42</td>
</tr>
<tr>
<td>3RA6400-1CB42</td>
<td>3RA6400-2CB42</td>
</tr>
<tr>
<td>3RA6400-1DB42</td>
<td>3RA6400-2DB42</td>
</tr>
<tr>
<td>3RA6400-1EB42</td>
<td>3RA6400-2EB42</td>
</tr>
</tbody>
</table>

For use in the infeed system for 3RA6, without main circuit terminals with 1 pair of control circuit terminals

<table>
<thead>
<tr>
<th>Article No.</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>3RA6400-1AB43</td>
<td>3RA6400-2AB43</td>
</tr>
<tr>
<td>3RA6400-1BB43</td>
<td>3RA6400-2BB43</td>
</tr>
<tr>
<td>3RA6400-1CB43</td>
<td>3RA6400-2CB43</td>
</tr>
<tr>
<td>3RA6400-1DB43</td>
<td>3RA6400-2DB43</td>
</tr>
<tr>
<td>3RA6400-1EB43</td>
<td>3RA6400-2EB43</td>
</tr>
</tbody>
</table>

1) The actual starting and rated data of the motor to be protected must be considered when selecting the units.
### Selection and ordering data (continued)

#### 3RA65 reversing starters

**Rated control supply voltage** 24 V DC  
Width 90 mm  
Rated short-circuit current $I_{CS} = 53$ kA at 400 V  
Two sets of 3RA6940-0A adapters are required for screw fixing.

![3RA65 with 3RA6911-1A auxiliary switch blocks](image)

<table>
<thead>
<tr>
<th>Standard three-phase motor</th>
<th>Setting range for solid-state overload release</th>
<th>Instantaneous overcurrent release</th>
<th>Screw terminals</th>
<th>Spring-type terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td>4-pole at 400 V AC(^1)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>Standard output (P)</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>kW</td>
<td>A</td>
<td>I &gt;</td>
<td>Article No.</td>
<td>Article No.</td>
</tr>
<tr>
<td>0.09</td>
<td>0.1 ... 0.4</td>
<td>56</td>
<td>3RA6500-1AB42</td>
<td>3RA6500-2AB42</td>
</tr>
<tr>
<td>0.37</td>
<td>0.32 ... 1.25</td>
<td>56</td>
<td>3RA6500-1BB42</td>
<td>3RA6500-2BB42</td>
</tr>
<tr>
<td>1.5</td>
<td>1 ... 4</td>
<td>56</td>
<td>3RA6500-1CB42</td>
<td>3RA6500-2CB42</td>
</tr>
<tr>
<td>5.5</td>
<td>3 ... 12</td>
<td>168</td>
<td>3RA6500-1DB42</td>
<td>3RA6500-2DB42</td>
</tr>
<tr>
<td>15</td>
<td>8 ... 32</td>
<td>448</td>
<td>3RA6500-1EB42</td>
<td>3RA6500-2EB42</td>
</tr>
</tbody>
</table>

**For standard mounting rail or screw fixing, including 1 pair of main circuit terminals and 1 pair of control circuit terminals**

<table>
<thead>
<tr>
<th>kW</th>
<th>A</th>
<th>I &gt;</th>
<th>Article No.</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.09</td>
<td>0.1 ... 0.4</td>
<td>56</td>
<td>3RA6500-1AB43</td>
<td>3RA6500-2AB43</td>
</tr>
<tr>
<td>0.37</td>
<td>0.32 ... 1.25</td>
<td>56</td>
<td>3RA6500-1BB43</td>
<td>3RA6500-2BB43</td>
</tr>
<tr>
<td>1.5</td>
<td>1 ... 4</td>
<td>56</td>
<td>3RA6500-1CB43</td>
<td>3RA6500-2CB43</td>
</tr>
<tr>
<td>5.5</td>
<td>3 ... 12</td>
<td>168</td>
<td>3RA6500-1DB43</td>
<td>3RA6500-2DB43</td>
</tr>
<tr>
<td>15</td>
<td>8 ... 32</td>
<td>448</td>
<td>3RA6500-1EB43</td>
<td>3RA6500-2EB43</td>
</tr>
</tbody>
</table>

**For use in the infeed system for 3RA6, without main circuit terminals with 1 pair of control circuit terminals**

<table>
<thead>
<tr>
<th>kW</th>
<th>A</th>
<th>I &gt;</th>
<th>Article No.</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.09</td>
<td>0.1 ... 0.4</td>
<td>56</td>
<td>3RA6500-1AB43</td>
<td>3RA6500-2AB43</td>
</tr>
<tr>
<td>0.37</td>
<td>0.32 ... 1.25</td>
<td>56</td>
<td>3RA6500-1BB43</td>
<td>3RA6500-2BB43</td>
</tr>
<tr>
<td>1.5</td>
<td>1 ... 4</td>
<td>56</td>
<td>3RA6500-1CB43</td>
<td>3RA6500-2CB43</td>
</tr>
<tr>
<td>5.5</td>
<td>3 ... 12</td>
<td>168</td>
<td>3RA6500-1DB43</td>
<td>3RA6500-2DB43</td>
</tr>
<tr>
<td>15</td>
<td>8 ... 32</td>
<td>448</td>
<td>3RA6500-1EB43</td>
<td>3RA6500-2EB43</td>
</tr>
</tbody>
</table>

\(^1\) The actual starting and rated data of the motor to be protected must be considered when selecting the units.
Overview

Accessories for SIRIUS 3RA6 compact starters in IO-Link version

The following accessories are available specially for the 3RA64, 3RA65 compact starters:

- The 4SI SIRIUS electronic module as IO-Link master allows for the simple and economical connection of SIRIUS controls with IO-Link (e.g. up to four groups of 4 compact starters) to the multifunctional SIMATIC ET 200S distributed I/O system.
- Additional connection cables for side-by-side mounting of up to 4 compact starters
- Operator panel for on-site control and diagnostics of up to 4 compact starters coupled to each other

Note

Accessories for all 3RA6 SIRIUS compact starters, see Chapter 4 "AS-Interface" ⇒ "3RA6 Compact Starters" ⇒ "Accessories"

Selection and ordering data

<table>
<thead>
<tr>
<th>Version</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Accessories especially for 3RA64, 3RA65 compact starters for IO-Link</td>
<td></td>
</tr>
<tr>
<td>Additional connection cables (flat) for side-by-side mounting of up to 4 compact starters</td>
<td></td>
</tr>
<tr>
<td>• 10-pole</td>
<td></td>
</tr>
<tr>
<td>- 8 mm(^1)</td>
<td></td>
</tr>
<tr>
<td>- 200 mm(^1)</td>
<td></td>
</tr>
<tr>
<td>• 14-pole</td>
<td></td>
</tr>
<tr>
<td>- 8 mm(^2)</td>
<td></td>
</tr>
<tr>
<td>- 200 mm</td>
<td></td>
</tr>
<tr>
<td>10-pole, 2,000 mm</td>
<td></td>
</tr>
<tr>
<td>3RA6932-0A</td>
<td></td>
</tr>
<tr>
<td>3RA6933-0B</td>
<td></td>
</tr>
<tr>
<td>3RA6931-0A</td>
<td></td>
</tr>
<tr>
<td>3RA6933-0C</td>
<td></td>
</tr>
<tr>
<td>Operator panel</td>
<td></td>
</tr>
<tr>
<td>(incl. enabling module, blanking cover and mounting bracket)</td>
<td></td>
</tr>
<tr>
<td>3RA6935-0A</td>
<td></td>
</tr>
<tr>
<td>Enabling module</td>
<td></td>
</tr>
<tr>
<td>3RA6936-0A</td>
<td></td>
</tr>
<tr>
<td>Blanking cover</td>
<td></td>
</tr>
<tr>
<td>3RA6936-0B</td>
<td></td>
</tr>
<tr>
<td>Connection cable (round) for connecting the operator panel</td>
<td></td>
</tr>
<tr>
<td>3RA6933-0A</td>
<td></td>
</tr>
</tbody>
</table>

\(^1\) 10-pole connection cables are required for EMERGENCY-STOP group concepts.

\(^2\) Is included in the scope of supply of the SIRIUS 3RA6 compact starter in IO-Link version.
IO-Link
SIRIUS 3RR24 monitoring relays for mounting onto 3RT2 contactors for IO-Link

General data

Overview

Features | 3RR24 | Benefits
--- | --- | ---
**General data**

**Sizes**
Dimensions in mm (W x H x D)
- Screw terminals
- Spring-type terminals

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
</table>
| S00, S0 | ✓ | Are coordinated with the dimensions, connections and technical characteristics of the other devices in the SIRIUS modular system (contactors, soft starters, etc.)
| S00: 45 x 79 x 80, S0: 45 x 87 x 91 | ✓ | Permit the mounting of slim and compact load feeders in widths of 45 mm (S00 and S0)
| S00: 45 x 90 x 80, S0: 45 x 109 x 92 | ✓ | Simplify configuration

**Current range**

<p>| | | |</p>
<table>
<thead>
<tr>
<th></th>
<th></th>
<th></th>
</tr>
</thead>
</table>
| S00: 1.6 ... 16 A, S0: 4 ... 40 A | ✓ | Is adapted to the other devices in the SIRIUS modular system
| | | Just a single version per size with a wide setting range enables easy configuration

**Permissible ambient temperature**

| During operation | -25 ... +60 °C | Suitable for applications in the control cabinet, worldwide

**Monitoring functions**

**Current overshoot**
✓ (Three-phase)
- Provides optimum inverse-time delayed protection of loads against excessive temperature rises due to overload
- Enables detection of filter blockages or pumping against closed gate valves
- Enables drawing conclusions about wear, poor lubrication or other maintenance-relevant phenomena

**Current undershoot**
✓ (Three-phase)
- Enables detection of overload due to a slipping or torn belt
- Guarantees protection of pumps against dry running
- Facilitates monitoring of the functions of resistive loads such as heaters
- Permits energy savings through monitoring of no-load operation

**Apparent current monitoring**
✓ (selectable)
- Precision current monitoring especially in a motor’s rated and upper torque range

**Active current monitoring**
✓ (selectable)
- Optimum current monitoring over a motor’s entire torque range through the patented combination of power factor and apparent current monitoring

**Range monitoring**
✓ (Three-phase)
- Simultaneous monitoring of current overshoot and undershoot with a single device

**Phase failure, open circuit**
✓ (Three-phase)
- Minimizes heating of three-phase motors during phase failure through immediate disconnection
- Prevents operation of hoisting equipment with reduced load carrying capacity

**Phase sequence monitoring**
✓ (selectable)
- Prevents starting of motors, pumps or compressors in the wrong direction of rotation

**Internal ground-fault detection (residual current monitoring)**
✓ (selectable)
- Provides optimum protection of loads against high-resistance short circuits or ground faults due to moisture, condensed water, damage to the insulation material, etc.
- Eliminates the need for additional special equipment
- Saves space in the control cabinet
- Reduces wiring overhead and costs

**Blocking current monitoring**
✓ (selectable)
- Minimizes heating of three-phase motors when blocked during operation through immediate disconnection
- Minimizes mechanical loading of the system by acting as an electronic shear pin

**Operating hours counter**
✓
- Gives the time during which there was a measurable current in at least 2 current paths
- As an indicator for upcoming maintenance or replacement of machine and system components

**Operating cycles counter**
✓
- Is incremented by one each time a breaking operation is detected, in other words a transition from three-phase current flow to no measurable current flow
- As an indicator for upcoming maintenance or replacement of contact blocks

✓ Available
## Overview (continued)

<table>
<thead>
<tr>
<th>Features</th>
<th>3RR24</th>
<th>Benefits</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Features</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>RESET function</strong></td>
<td>✓</td>
<td>• Allows manual or automatic resetting of the relay</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Resetting directly on the device, by switching the control supply voltage off and on or via IO-Link (remote RESET)</td>
</tr>
<tr>
<td><strong>ON-delay time</strong></td>
<td>0 ... 999.9 s</td>
<td>• Enables motor starting without evaluation of the starting current</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Can be used for monitoring motors with lengthy start-up</td>
</tr>
<tr>
<td><strong>Tripping delay time</strong></td>
<td>0 ... 999.9 s</td>
<td>• Permits brief threshold value violations during operation</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Prevents frequent warnings and disconnections with currents near the threshold values</td>
</tr>
<tr>
<td><strong>Operating and indicating elements</strong></td>
<td>Displays and buttons</td>
<td>• For setting the threshold values and delay times</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• For selectable functions</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• For quick and selective diagnostics</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Displays for permanent display of measured values</td>
</tr>
<tr>
<td><strong>Integrated contacts</strong></td>
<td>1 CO contact, 1 semiconductor output (in SIO mode)</td>
<td>• Enable disconnection of the system or process when there is an irregularity</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Can be used to output signals</td>
</tr>
<tr>
<td><strong>Design of load feeders</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Short-circuit strength up to 100 kA at 690 V</strong></td>
<td>✓</td>
<td>• Provides optimum protection of the loads and operating personnel in the event of short circuits due to insulation faults or faulty switching operations</td>
</tr>
<tr>
<td>(in conjunction with the corresponding fuses or the corresponding motor starter protector)</td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Electrical and mechanical matching to 3RT2 contactors</strong></td>
<td>✓</td>
<td>• Simplifies configuration</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Reduces wiring outlay and costs</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Enables stand-alone installation as well as space-saving direct mounting</td>
</tr>
<tr>
<td><strong>Spring-type terminals for main circuit and auxiliary circuits</strong></td>
<td>✓ (optional)</td>
<td>• Enables fast connections</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Permits vibration-resistant connections</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Enables maintenance-free connections</td>
</tr>
<tr>
<td><strong>Other features</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td><strong>Suitable for single- and three-phase loads</strong></td>
<td>✓</td>
<td>• Enables the monitoring of single-phase systems through parallel infeed at the contactor or looping the current through the three phase connections</td>
</tr>
<tr>
<td><strong>Wide setting ranges</strong></td>
<td>✓</td>
<td>• Reduce the number of variants</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Minimize the configuration outlay and costs</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Minimize storage overheads, storage costs, tied-up capital</td>
</tr>
<tr>
<td><strong>Power supply</strong></td>
<td>24 V DC</td>
<td>• Direct via IO-Link master or via an external auxiliary voltage independent of the IO-Link</td>
</tr>
<tr>
<td></td>
<td></td>
<td>• Minimizes the configuring overhead and costs</td>
</tr>
</tbody>
</table>

✓ Available
IO-Link
SIRIUS 3RR24 monitoring relays for mounting onto 3RT2 contactors for IO-Link

General data

Overview (continued)

Possible combinations of 3RR24 monitoring relays with 3RT2 contactors for IO-Link

<table>
<thead>
<tr>
<th>Monitoring relays</th>
<th>Current range</th>
<th>Contactors (type, size, rating)</th>
</tr>
</thead>
<tbody>
<tr>
<td>3RR2441</td>
<td>1.6 ... 16</td>
<td>✓ 3RT201 S00 3/4/5.5/7.5 kW</td>
</tr>
<tr>
<td>3RR2442</td>
<td>4 ... 40</td>
<td>✓ With stand-alone installation support</td>
</tr>
</tbody>
</table>

Available

Notes:
Devices required for the communication via IO-Link:
- Any controller that supports the IO-Link (e.g. ET 200S with CPU or S7-1200), see Catalog ST 70 "Products for Totally Integrated Automation"
- IO-Link master (e.g. 4SI or 4SI IO-Link electronic module for SIMATIC ET200S or SM 1278 for S7-1200) see Catalog ST 70 "Products for Totally Integrated Automation"

Each monitoring relay requires an IO-Link channel.

Connection methods
Selection tables for the 3RR24 monitoring relays can be found on the following pages.

- Screw terminals
- Spring-type terminals

More information

Notes on safety:
System networking requires suitable protective measures (including network segmentation for IT security) in order to ensure safe plant operation, see www.siemens.com/industrialsecurity.

More information about the subject of Industrial Security see www.siemens.com/industrialsecurity.
Overview

SIRIUS 3RR2441 and 3RR2442 current monitoring relay

The SIRIUS 3RR24 current monitoring relays for IO-Link are suitable for the load monitoring of motors or other loads. In three phases they monitor the rms value of AC currents for overshooting or undershooting of set threshold values.

Whereas apparent current monitoring is used above all in connection with the rated torque or in case of overload, the active current monitoring option, which is also selectable, can be used to observe and evaluate the load factor over a motor’s entire torque range.

The 3RR24 current monitoring relays for IO-Link can be integrated directly in the feeder by mounting onto the 3RT2 contactor; separate wiring of the main circuit is therefore superfluous. No separate transformers are required.

For a line-oriented configuration or simultaneous use of an overload relay, terminal supports for stand-alone installation are available for separate standard rail mounting.

The SIRIUS 3RR24 current monitoring relays for IO-Link also offer many other options based upon the monitoring functions of the conventional SIRIUS 3RR2 monitoring relays:

- Measured value transmission to a controller, including resolution and unit, may be parameterizable as to which value is cyclically transmitted
- Transmission of alarm flags to a controller
- Full diagnosis capability by inquiry as to the cause of the fault in the diagnosis data record
- Remote parameterization is also possible, in addition to or instead of local parameterization
- Rapid parameterization of the same devices by duplication of the parameterization in the controller
- Parameter transmission by upload to a controller by IO-Link call or by parameter server (if IO-Link master from IO-Link Specification V 1.1 and higher is used)
- Consistent central data storage in the event of parameter change locally or via a controller
- Automatic reparameterizing when devices are exchanged
- Blocking of local parameterization via IO-Link possible
- Faults are saved in parameterizable and non-volatile fashion to prevent an automatic start-up after voltage failure and to make sure diagnostics data is not lost
- By integration into the automation level the option exists of parameterizing the monitoring relay at any time via a display unit or displaying the measured values in a control room or locally at the machine/control cabinet.

Even without communication via IO-Link the devices continue to function fully autonomously:

- Parameterization can take place locally at the device, independently of a controller.
- In the event of failure or before the controller becomes available the monitoring relays work as long as the control supply voltage (24 V DC) is present.
- If the monitoring relays are operated without the controller, the 3RR24 monitoring relays for IO-Link have, thanks to the integrated SIO mode, an additional semiconductor output, which switches when the adjustable warning threshold is exceeded.

Thanks to the combination of autonomous monitoring relay function and integrated IO-Link communication, redundant sensors and/or analog signal converters – which previously took over the transmission of measured values to a controller, leading to considerable extra cost and wiring outlay – are no longer needed.

Because the output relays are still present, the monitoring relays increase the functional reliability of the system, since the controller can only fulfill the control tasks if the current measured values are available, whereas the output relays can also be used for the disconnection of the system if limit values that cannot be reached during operation are exceeded.

For further information on the IO-Link communication system, see page 5/2 onwards.
IO-Link
SIRIUS 3RR24 monitoring relays for mounting onto 3RT2 contactors for IO-Link

Current and active current monitoring

Benefits
- Can be mounted directly on 3RT2 contactors and 3RA23 reversing contactor assemblies, in other words, there is no need for additional wiring in the main circuit
- Optimally coordinated with the technical characteristics of the 3RT2 contactors
- No separate current transformer required
- Variably adjustable to overshoot, undershoot or range monitoring
- Freely configurable delay times and RESET response
- Display of ACTUAL value and status messages
- All versions with removable control current terminals
- All versions with screw or spring-type terminals
- Simple determination of the threshold values through direct reference to actually measured values for setpoint loading
- Range monitoring and selectable active current measurement mean that only one device for monitoring a motor is required along the entire torque curve
- In addition to current monitoring it is also possible to monitor for current unbalance, broken cables, phase failure, phase sequence, residual current and motor blocking.
- Integrated counter for operating cycles counter and operating hours to support requirements-based maintenance of the monitored machine or application
- Simple cyclical transmission of the current measured values, relay switching states and events to a controller
- Remote parameterization
- Automatic reparameterizing when devices are exchanged
- Simple duplication of identical or similar parameterizations
- Reduction of control current wiring
- Elimination of testing costs and wiring errors
- Reduction of configuration work
- Integration in TIA means clear diagnostics if a fault occurs
- Cost saving and space saving in control cabinet due to the elimination of AI and IO modules as well as analog signal converters and duplicated sensors

Application
- Monitoring of current overshoot and undershoot
- Monitoring of broken conductors
- Monitoring of no-load operation and load shedding, e.g. in the event of a torn V-belt or no-load operation of a pump
- Monitoring of overload, e.g. on pumps due to a dirty filter system
- Monitoring the functionality of electrical loads such as heaters
- Monitoring of wrong phase sequence on mobile equipment such as compressors or cranes
- Monitoring of high-impedance short-circuits, e.g. due to damaged insulation or moisture

The use of SIRIUS monitoring relays for IO-Link is particularly recommended for machines and plant in which these relays, in addition to their monitoring function, are to be connected to the automation level for the rapid, simple and fault-free provision of the current measured values and/or for remote parameterization.

The monitoring relays can either relieve the controller of monitoring tasks or, as a second monitoring entity in parallel to and independent of the controller, increase the reliability in the process or in the system. In addition, the elimination of AI and IO modules allows the width of the controller to be reduced despite significantly expanded functionality.
Selection and ordering data

**SIRIUS 3RR24 current monitoring relays for IO-Link**

- For load monitoring of motors or other loads
- Multi-phase monitoring of undervoltage and overvoltage
- Starting and tripping delay can be adjusted separately
- Tripping delay 0 to 999.9 s
- Auto or Manual RESET

<table>
<thead>
<tr>
<th>Size</th>
<th>Measuring range</th>
<th>Hysteresis</th>
<th>Control supply voltage ( U_s )</th>
<th>Screw terminals</th>
<th>Spring-type terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td>S00</td>
<td>1.6 ... 16</td>
<td>0.1 ... 3</td>
<td>24 DC</td>
<td>3RR2441-1AA40</td>
<td>3RR2441-2AA40</td>
</tr>
<tr>
<td>S0</td>
<td>4 ... 40</td>
<td>0.1 ... 8</td>
<td>24 DC</td>
<td>3RR2442-1AA40</td>
<td>3RR2442-2AA40</td>
</tr>
</tbody>
</table>

Digitally adjustable, LCD, open-circuit or closed-circuit principle, 1 CO, 1 semiconductor output (in SIO mode), 3-phase current monitoring, active current or apparent current monitoring, current unbalance monitoring, phase sequence monitoring, residual current monitoring, blocking current monitoring, operating hours counter, operating cycles counter, reclosing delay time 0 ... 999.9 min, start-up delay 0 ... 999.9 s, separate settings for warning and alarm thresholds.
## IO-Link

SIRIUS 3RR24 monitoring relays for mounting onto 3RT2 contactors for IO-Link

### Current and active current monitoring

#### Accessories

<table>
<thead>
<tr>
<th>Use</th>
<th>Version</th>
<th>Size</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Terminal supports for stand-alone installation(^1)</td>
<td>For 3RR24</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>For separate mounting of the overload relays or monitoring relays; screw and snap-on mounting onto TH 3S standard mounting rail according to IEC 60715</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>• Screw connection</td>
<td>S00</td>
<td>S0U2916-3AA01</td>
</tr>
<tr>
<td></td>
<td>• Spring-type connection</td>
<td>S00</td>
<td>S0U2926-3AC01</td>
</tr>
<tr>
<td></td>
<td>3RU2916-3AA01</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3RU2926-3AC01</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Blank labels</td>
<td>For 3RR24</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Unit labeling plates(^2)</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>For SIRIUS devices</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>20 mm x 7 mm, titanium gray</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3RT2900-1SB20</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Sealable covers</td>
<td>For 3RR24</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Sealable covers</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>For securing against unintentional or unauthorized adjustment of settings</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3RR2940</td>
<td></td>
<td></td>
</tr>
<tr>
<td>Tools for opening spring-type terminals</td>
<td>For auxiliary circuit connections</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>Screwdrivers</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>For all SIRIUS devices with spring-type terminals, 3.0 mm x 0.5 mm, length approx. 200 mm, titanium gray/black, partially insulated</td>
<td></td>
<td></td>
</tr>
<tr>
<td></td>
<td>3RA2908-1A</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

\(^1\) The accessories are identical to those of the 3RU21 thermal overload relays and the 3RB3 solid-state overload relays, see Catalog IC 10, Chapter 7 “Protection Equipment”.

\(^2\) PC labeling system for individual inscription of unit labeling plates available from: murrplastik Systemtechnik GmbH see Catalog IC 10, Chapter 16, “Appendix” ⇒ “External Partners”.

---
Overview

SIRIUS 3UG48 monitoring relays

The SIRIUS 3UG48 monitoring relays for electronic and mechanical variables monitor all important characteristics that allow conclusions to be drawn about the functionality of a plant. Both sudden disturbances and gradual changes, which may indicate the need for maintenance, are detected.

Thanks to their relay outputs, the monitoring relays permit direct disconnection of the affected system components as well as alerting e.g. by triggering a warning light. Thanks to adjustable delay times the 3UG4 monitoring relays can respond very flexibly to brief faults such as voltage dips or load changes and can thus avoid unnecessary alarms and disconnections and increase system availability.

3UG48 monitoring relays for IO-Link

The SIRIUS 3UG48 monitoring relays for IO-Link also offer many other options based upon the monitoring functions of the tried-and-tested SIRIUS 3UG4 monitoring relays:

- Measured value transmission to a controller, including resolution and unit, may be parameterizable as to which value is cyclically transmitted
- Transmission of alarm flags to a controller
- Full diagnosis capability by inquiry as to the cause of the fault in the diagnosis data record
- Remote parameterization is also possible, in addition to or instead of local parameterization
- Rapid parameterization of the same devices by duplication of the parameterization in the controller
- Parameter transmission by upload to a controller by IO-Link call or by parameter server (if IO-Link master from IO-Link Specification V 1.1 and higher is used)
- Consistent central data storage in the event of parameter change locally or via a controller
- Automatic reparameterizing when devices are exchanged
- Blocking of local parameterization via IO-Link possible
- Faults are saved in parameterizable and non-volatile fashion to prevent an automatic start-up after voltage failure and to make sure diagnostics data is not lost
- Integration into the automation level provides the option of parameterizing the monitoring relays at any time via a display unit, or displaying the measured values in a control room or locally at the machine/control cabinet.

Even without communication via IO-Link the devices continue to function fully autonomously:

- Parameterization can take place locally at the device, independently of a controller.
- In the event of failure or before the controller becomes available the monitoring relays work as long as the control supply voltage (24 V DC) is present.
- If the monitoring relays are operated without the controller, the 3UG48 monitoring relays have, thanks to the integrated SIO mode, an additional semiconductor output, which switches when the adjustable warning threshold is exceeded.

Thanks to the combination of autonomous monitoring relay function and integrated IO-Link communication, redundant sensors and/or analog signal converters – which previously took over the transmission of measured values to a controller, leading to considerable extra cost and wiring outlay – are no longer needed.

Because the output relays are still present, the monitoring relays increase the functional reliability of the system, since the controller can only fulfill the control tasks if the current measured values are available, whereas the output relays can also be used for the disconnection of the system if limit values that cannot be reached during operation are exceeded.

The individual 3UG48 monitoring relays for IO-Link offer the following functions in different combinations:

- Phase sequence
- Phase failure, neutral conductor failure
- Phase asymmetry
- Undershooting and/or overshooting of limit values for voltage
- Undershooting and/or overshooting of limit values for current
- Undershooting and/or overshooting of power factor limit values
- Monitoring of the active current or the apparent current
- Monitoring of the residual current
- Undershooting and/or overshooting of limit values for speed

Note:
Further information on the IO-Link bus system see page 5/2 onwards.

Notes on safety:
System networking requires suitable protective measures (including network segmentation for IT security) in order to ensure safe plant operation.

More information about the subject of Industrial Security see www.siemens.com/industrialsecurity.
**Overview** (continued)

**Use of conventional monitoring relays**

**Notes:**

- Devices required for the communication via IO-Link:
  - Any controller that supports the IO-Link (e.g. ET 200S with CPU or S7-1200), see Catalog ST 70 "Products for Totally Integrated Automation"
  - IO-Link master (e.g. 4SI or 4SI IO-Link electronic module for SIMATIC ET200S or SM 1278 for S7-1200) see Catalog ST 70 "Products for Totally Integrated Automation"

Each monitoring relay requires an IO-Link channel.

**Connection methods**

Selection tables for the 3UG48 monitoring relays can be found on the following pages.

- Screw terminals
- Spring-type terminals
Benefits

- Simple cyclical transmission of the current measured values, relay switching states and events to a controller
- Remote parameterization
- Automatic reparameterizing when devices are exchanged
- Simple duplication of identical or similar parameterizations
- Reduction of control current wiring
- Elimination of testing costs and wiring errors
- Reduction of configuration work
- Integration in TIA means clear diagnostics if a fault occurs
- Cost saving and space saving in control cabinet due to the elimination of AI and IO modules as well as analog signal converters and duplicated sensors

Application

The use of SIRIUS monitoring relays for IO-Link is particularly recommended for machines and plant in which these relays, in addition to their monitoring function, are to be connected to the automation level for the rapid, simple and fault-free provision of the current measured values and/or for remote parameterization.

The monitoring relays can either relieve the controller of monitoring tasks or, as a second monitoring entity in parallel to and independent of the controller, increase the reliability in the process or in the system. In addition, the elimination of AI and IO modules allows the width of the controller to be reduced despite significantly expanded functionality.

More information


Notes on safety:
System networking requires suitable protective measures (including network segmentation for IT security) in order to ensure safe plant operation.

More information about the subject of Industrial Security see www.siemens.com/industrialsecurity.
IO-Link
SIRIUS 3UG48 monitoring relays for stand-alone installation for IO-Link

Line monitoring

Overview

SIRIUS 3UG4815 monitoring relay

Solid-state line monitoring relays provide maximum protection for mobile machines, plants and hoisting equipment or for unstable networks. Network and voltage faults can thus be detected early and rectified before far greater damage ensues.

The line monitoring relays with IO-Link monitor phase sequence, phase failure (with or without N conductor monitoring), phase asymmetry and undervoltage and/or overvoltage.

Phase asymmetry is evaluated as the difference between the greatest and the smallest phase voltage relative to the greatest phase voltage. Undervoltage or overvoltage exist if the set limit values for at least one phase voltage are overshot or undershot. The rms value of the voltage is measured.

Benefits

- Can be used in any network from 160 to 630 V AC worldwide thanks to wide voltage range
- Variably adjustable to overshoot, undershoot or range monitoring
- Freely configurable delay times and RESET response
- Width 22.5 mm
- Display and transmission of actual value and network fault type to controller
- All versions with removable terminals
- All versions with screw or spring-type terminals

Application

The relays are used above all for mobile equipment, e.g. air conditioning compressors, refrigerating containers, building site compressors and cranes.

Selection and ordering data

- Adjustable via IO-Link and locally, with illuminated LCD
- Power supply with 24 V DC via IO-Link or external auxiliary voltage
- Auto or Manual RESET
- Open or closed-circuit principle
- 1 CO contact, 1 semiconductor output (in SIO mode)

Function

<table>
<thead>
<tr>
<th>Function</th>
<th>Application</th>
</tr>
</thead>
<tbody>
<tr>
<td>Phase sequence</td>
<td>• Direction of the drive</td>
</tr>
<tr>
<td>Phase failure</td>
<td>• A fuse has tripped</td>
</tr>
<tr>
<td></td>
<td>• Failure of the control supply voltage</td>
</tr>
<tr>
<td></td>
<td>• Broken cable</td>
</tr>
<tr>
<td>Phase asymmetry</td>
<td>• Overheating of the motor due to asymmetrical voltage</td>
</tr>
<tr>
<td></td>
<td>• Detection of asymmetrically loaded networks</td>
</tr>
<tr>
<td>Undervoltage</td>
<td>• Increased current on a motor with corresponding overheating</td>
</tr>
<tr>
<td></td>
<td>• Unintentional resetting of a device</td>
</tr>
<tr>
<td></td>
<td>• Network collapse, particularly with battery power</td>
</tr>
<tr>
<td>Overvoltage</td>
<td>• Protection of a plant against destruction due to overvoltage</td>
</tr>
</tbody>
</table>

Measurable mains voltage

<table>
<thead>
<tr>
<th>Adjustable hysteresis</th>
<th>Under-voltage detection</th>
<th>Over-voltage detection</th>
<th>Stabilization time adjustable for DEL</th>
<th>Tripping delay time adjustable for DEL</th>
<th>Version of auxiliary contacts</th>
<th>Measurable mains voltage</th>
</tr>
</thead>
<tbody>
<tr>
<td>V s s V AC</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

Monitoring of phase sequence, phase failure, phase asymmetry, overvoltage and undervoltage

1 ... 20 ✓ ✓ 0.1 ... 999.9 0.1 ... 999.9 1 CO + 1 Q2) 160 ... 690

3UG4815-1AA40 3UG4815-2AA40

Monitoring of phase sequence, phase and N conductor failure, phase asymmetry, overvoltage and undervoltage

1 ... 20 ✓ ✓ 0.1 ... 999.9 0.1 ... 999.9 1 CO + 1 Q2) 90 ... 400 to N

3UG4816-1AA40 3UG4816-2AA40

✓ Function available

1) Absolute limit values.
2) In SIO mode.

For accessories see page 5/53.
## Overview

SIRIUS 3UG4832 monitoring relays

The relays monitor single-phase AC voltages (rms value) and DC voltages against the set limit value for overshoot and undershoot.

## Benefits

- Variably adjustable to overshoot, undershoot or range monitoring
- Freely configurable delay times and RESET response
- Width 22.5 mm
- Display and transmission of actual value and status messages to controller
- All versions with removable terminals
- All versions with screw or spring-type terminals

## Application

- Protection of a plant against destruction due to overvoltage
- Switch-on of a plant at a defined voltage and higher
- Protection from undervoltage due to overloaded control supply voltages, particularly with battery power

## Selection and ordering data

- Adjustable via IO-Link and locally, with illuminated LCD
- Power supply with 24 V DC via IO-Link or external auxiliary voltage
- Auto or Manual RESET
- Open or closed-circuit principle
- 1 CO contact, 1 semiconductor output (in SIO mode)

### Measuring range

<table>
<thead>
<tr>
<th>Measuring range</th>
<th>Adjustable hysteresis</th>
<th>ON-delay time adjustable</th>
<th>Tripping delay time separately adjustable</th>
</tr>
</thead>
<tbody>
<tr>
<td>V AC/DC</td>
<td>V</td>
<td>s</td>
<td>s</td>
</tr>
</tbody>
</table>

### Monitoring of voltage for overshoot and undershoot

<table>
<thead>
<tr>
<th>Monitoring of voltage for overshoot and undershoot</th>
<th>3UG4832-1AA40</th>
<th>3UG4832-2AA40</th>
</tr>
</thead>
<tbody>
<tr>
<td>10 ... 600</td>
<td>0.1 ... 300</td>
<td>0 ... 999.9</td>
</tr>
<tr>
<td>0.1 ... 300</td>
<td>0 ... 999.9</td>
<td></td>
</tr>
</tbody>
</table>

For accessories see page 5/53.
IO-Link
SIRIUS 3UG48 monitoring relays for stand-alone installation for IO-Link

Current monitoring

Overview

SIRIUS 3UG4822 monitoring relays

The relays monitor single-phase AC (rms value) and DC currents against the set limit value for overshoot and undershoot.

Benefits

- Variably adjustable to overshoot, undershoot or range monitoring
- Freely configurable delay times and RESET response
- Width 22.5 mm
- Display and transmission of actual value and status messages to controller
- All versions with removable terminals
- All versions with screw or spring-type terminals

Application

- Overcurrent and undercurrent monitoring
- Monitoring the functionality of electrical loads
- Monitoring for broken conductors

Selection and ordering data

- Adjustable via IO-Link and locally, with illuminated LCD
- Power supply with 24 V DC via IO-Link or external auxiliary voltage
- Adjustable converter factor to display the measured primary current when external current transformer used
- Auto or Manual RESET
- Open or closed-circuit principle
- 1 CO contact, 1 semiconductor output (in SIO mode)

Selection and ordering data table:

<table>
<thead>
<tr>
<th>Measuring range AC/DC</th>
<th>Adjustable hysteresis</th>
<th>ON-delay time adjustable onDel</th>
<th>Tripping delay time separable adjustable U▲Del/U▼Del</th>
<th>Screw terminals</th>
<th>Spring-type terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td>A</td>
<td></td>
<td>s</td>
<td>s</td>
<td>Article No.</td>
<td>Article No.</td>
</tr>
</tbody>
</table>

Article No.: 3UG4822-1AA40 3UG4822-2AA40

Monitoring of current for overshooting and undershooting

<table>
<thead>
<tr>
<th>Measuring range</th>
<th>Adjustable hysteresis</th>
<th>ON-delay time adjustable onDel</th>
<th>Tripping delay time separable adjustable U▲Del/U▼Del</th>
</tr>
</thead>
<tbody>
<tr>
<td>0.05 ... 10</td>
<td>0.01 ... 5</td>
<td>0.1 ... 999.9</td>
<td>0.1 ... 999.9</td>
</tr>
</tbody>
</table>

For accessories see page 5/53.

For AC currents $I > 10$ A it is possible to use commercially available current transformers, e.g. the Siemens 4NC current transformer, as accessories, see Catalog LV 10, "Low-Voltage Power Distribution and Electrical Installation Technology".
### Overview

The 3UG4841 power factor and active current monitoring devices enable the load monitoring of motors. Whereas power factor monitoring is used above all for monitoring no-load operation, the active current monitoring option can be used to observe and evaluate the load factor over the entire torque range.

### Benefits

- Monitoring of even small single-phase motors with a no-load supply current below 0.5 A
- Simple determination of threshold values by the direct collection of measured variables on motor loading
- Range monitoring and active current measurement enable detection of cable breaks between control cabinets and motors, as well as phase failures
- Power factor and/or $I_{\text{res}}$ (active current) can be selected as the measurement principle
- Width 22.5 mm
- Display and transmission of actual value and status messages to controller
- All versions with removable terminals
- All versions with screw or spring-type terminals

### Application

- No-load monitoring and load shedding, such as in the event of a V-belt tear
- Underload monitoring in the low performance range, e.g. in the event of pump no-load operation
- Monitoring of overload, e.g. due to a dirty filter system
- Power factor monitoring in networks for control of compensation equipment
- Broken cable between control cabinet and motor

### Selection and ordering data

- For monitoring the power factor $\varphi$ and the active current $I_{\text{res}}$
- Suitable for single- and three-phase currents
- Adjustable via IO-Link and locally, with illuminated LCD
- Power supply with 24 V DC via IO-Link or external auxiliary voltage
- Overshoot, undershoot or range monitoring adjustable
- Upper and lower limit values can be adjusted separately
- Permanent display of actual value and tripping state
- 1 CO contact each for undershoot and overshoot, 1 semiconductor output (in SIO mode)

### Measuring range

<table>
<thead>
<tr>
<th>Measuring range</th>
<th>Voltage range of the measuring voltage</th>
<th>Hysteresis</th>
<th>ON-delay time adjustable onDel</th>
<th>Tripping delay time adjustable  (\uparrow)Del/(\downarrow)Del</th>
<th>Screw terminals</th>
<th>Spring-type terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td>For power factor</td>
<td>For active current $I_{\text{res}}$ 50/60 Hz AC</td>
<td>Adjustable for power factor</td>
<td>Adjustable for active current $I_{\text{res}}$</td>
<td>P.t. A V P.t. A s s</td>
<td></td>
<td></td>
</tr>
<tr>
<td>PI. A V</td>
<td>PI. A s</td>
<td></td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

### Monitoring of power factor and active current for overshooting and undershooting

<table>
<thead>
<tr>
<th>Power factor PI. A V</th>
<th>1...0.99 0.2...10 90...690</th>
<th>Power factor PI. A s</th>
<th>0.1...0.2 0.1...3 0...999.9</th>
</tr>
</thead>
<tbody>
<tr>
<td>Active current PI. A s</td>
<td>0...999.9</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

1) Absolute limit values.

For accessories see page 5/53.

For AC active currents $I_{\text{res}} > 10$ A it is possible to use commercially available current transformers, e.g. Siemens 4NC current converter, as accessories, see Catalog LV 10 “Low-Voltage Power Distribution and Electrical Installation Technology”.

---

SIRIUS 3UG48 monitoring relay

For AC active currents $I_{\text{res}} > 10$ A it is possible to use commercially available current transformers, e.g. Siemens 4NC current converter, as accessories, see Catalog LV 10 “Low-Voltage Power Distribution and Electrical Installation Technology”.

---

© Siemens AG 2014

Siemens IK PI · 2015
IO-Link
SIRIUS 3UG48 monitoring relays for stand-alone installation for IO-Link
Residual current monitoring

Residual-current monitoring relays

Overview

The 3UG4825 residual-current monitoring relays are used in conjunction with the 3UL23 residual current transformers for monitoring plants in which higher residual currents are increas-
ingly expected due to environmental conditions. Monitoring encompasses pure AC residual currents or AC residual currents with a pulsating DC fault current component (transformer type A in accordance with DIN VDE 0100-530/IEC TR 60755).

Benefits

- High measuring accuracy ± 7.5%
- Permanent self-monitoring
- Parameterization of the devices locally or via IO-Link possible
- Variable threshold values for warning and disconnection
- Freely configurable delay times and RESET response
- Display and transmission of actual value and status messages to controller
- High level of flexibility and space saving through installation of the transformer inside or outside the control cabinet
- Width 22.5 m
- All versions with removable terminals
- All versions with screw or spring-type terminals

Application

Monitoring of plants in which residual currents can occur, e.g. due to dust deposits or moisture, porous cables and leads, or capacitive residual currents

Selection and ordering data

- For monitoring residual currents from 0.03 to 40 A, from 16 to 400 Hz
- For 3UL23 residual-current transformers with feed-through opening from 35 to 210 mm
- Permanent self-monitoring
- Certified in accordance with IEC 60947, functionality corres-
donds to IEC 62020
- Digitally adjustable, with illuminated LCD
- Permanent display of actual value and tripping state
- Separately adjustable limit value and warning threshold
- 1 changeover contact each for warning threshold and tripping threshold

For accessories see page 5/53.
3UL23 residual-current transformers and accessories for 3UL23 see page 5/51.
Overview

The 3UL23 residual-current transformers detect residual currents in machines and plants. They are suitable for pure AC residual currents or AC residual currents with a pulsating DC fault current component (transformer type A in accordance with DIN VDE 0100-530/IEC TR 60755).

Together with the 3UG4625, 3UG4825 residual-current monitoring relays for IO-Link or the SIMOCODE 3UF motor management and control device they enable residual-current and ground-fault monitoring.

The 3UL2302-1A and 3UL2303-1A residual-current transformers with a feed-through opening from 35 to 55 mm can be mounted in conjunction with the 3UL2900 accessories on a TH 35 standard mounting rail according to IEC 60715.

Selection and ordering data

<table>
<thead>
<tr>
<th>Diameter of the feed-through opening mm</th>
<th>Connectable cross-section of the connecting terminal mm²</th>
<th>Screw terminals Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Residual-current transformer (essential accessory for 3UG4625, 3UG4825 or SIMOCODE 3UF)</td>
<td></td>
<td></td>
</tr>
<tr>
<td>35</td>
<td>2.5</td>
<td>3UL2302-1A</td>
</tr>
<tr>
<td>55</td>
<td>2.5</td>
<td>3UL2303-1A</td>
</tr>
<tr>
<td>80</td>
<td>2.5</td>
<td>3UL2304-1A</td>
</tr>
<tr>
<td>110</td>
<td>2.5</td>
<td>3UL2305-1A</td>
</tr>
<tr>
<td>140</td>
<td>2.5</td>
<td>3UL2306-1A</td>
</tr>
<tr>
<td>210</td>
<td>4</td>
<td>3UL2307-1A</td>
</tr>
</tbody>
</table>

Accessories

<table>
<thead>
<tr>
<th>Version</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>Adapter</td>
<td>3UL2900</td>
</tr>
</tbody>
</table>

For mounting onto standard rail for 3UL23 to diameter 55 mm
IO-Link
SIRIUS 3UG48 monitoring relays for stand-alone installation for IO-Link

**Overview**

3UG4851 monitoring relays are used in combination with a sensor to monitor drives for overspeed and/or underspeed. Furthermore, the monitoring relays are ideal for all functions where a continuous pulse signal needs to be monitored (e.g. belt travel monitoring, completeness monitoring, passing monitoring, clock-time monitoring).

**Benefits**

- Variably adjustable to overshoot, undershoot or range monitoring
- Freely configurable delay times and RESET response
- Display and transmission of actual value and fault type to controller
- Use of up to 10 sensors per rotation for extremely slowly rotating motors
- 2- or 3-wire sensors and sensors with a mechanical switching output or solid-state-output can be connected
- Auxiliary voltage for sensor integrated
- All versions with removable terminals
- All versions with screw or spring-type terminals

**Application**

- Slip or tear of a belt drive
- Overload monitoring
- Transport monitoring for completeness

**Selection and ordering data**

- For speed monitoring in revolutions per minute (rpm)
- Two- or three-wire sensor with mechanical or electronic switching output can be connected
- Two-wire NAMUR sensor can be connected
- Sensor supply 24 V DC/50 mA integrated
- Input frequency 0.1 to 2 200 pulses per minute (0.0017 to 36.7 Hz)
- With or without enable signal for the drive to be monitored
- Adjustable via IO-Link and locally, with illuminated LCD

**Benefits**

- Power supply with 24 V DC via IO-Link or external auxiliary voltage
- Overshoot, undershoot or range monitoring adjustable
- Number of pulses per revolution can be adjusted
- Upper and lower limit values can be adjusted separately
- Auto, manual or remote RESET options after tripping
- Permanent display of actual value and tripping state
- 1 CO contact, 1 semiconductor output (in SIO mode)

<table>
<thead>
<tr>
<th>Measuring range</th>
<th>Adjustable hysteresis</th>
<th>ON-delay time adjustable onDel</th>
<th>Tripping delay time separately adjustable rpm ▲ Del∩ rpm ▼ Del</th>
<th>Pulses per revolution</th>
<th>Screw terminals</th>
<th>Spring-type terminals</th>
<th>CO</th>
</tr>
</thead>
<tbody>
<tr>
<td>rpm</td>
<td>rpm</td>
<td>s</td>
<td>s</td>
<td></td>
<td></td>
<td></td>
<td></td>
</tr>
</tbody>
</table>

**For accessories see page 5/53.**
## Selection and ordering data

<table>
<thead>
<tr>
<th>Use</th>
<th>Version</th>
<th>Description</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Blank labels</strong></td>
<td></td>
<td><strong>Unit labeling plates</strong></td>
<td>For SIRIUS devices&lt;br&gt;20 mm x 7 mm, titanium gray&lt;sup&gt;1)&lt;/sup&gt;</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>Adhesive labels</strong></td>
<td>For SIRIUS devices&lt;br&gt;19 mm x 6 mm, pastel turquoise&lt;br&gt;19 mm x 6 mm, zinc yellow</td>
</tr>
<tr>
<td><strong>Push-in lugs and covers</strong></td>
<td></td>
<td><strong>Push-in lugs</strong></td>
<td>For screw fixing, 2 units are required for each device</td>
</tr>
<tr>
<td></td>
<td></td>
<td><strong>Sealable covers</strong></td>
<td>For securing against unauthorized adjustment of setting knobs</td>
</tr>
<tr>
<td><strong>Tools for opening spring-type terminals</strong></td>
<td></td>
<td><strong>Screwdrivers</strong></td>
<td>For all SIRIUS devices with spring-type terminals&lt;br&gt;3.0 mm x 0.5 mm, length approx. 200 mm, titanium gray/black, partially insulated</td>
</tr>
</tbody>
</table>

<sup>1</sup> PC labeling system for individual inscription of unit labeling plates available from: murrplastik Systemtechnik GmbH see Catalog IC 10, Chapter 16, “Appendix” ⇒ “External Partners”.
**Overview**

SIRIUS 3RS14, 3RS15 temperature monitoring relays for IO-Link

The temperature monitoring relays for IO-Link are used to measure temperatures in solid, liquid and gas media. The temperature is calculated using a sensor in the medium, evaluated by the device and monitored up to two limit values for overshooting or undershooting a working range (window function).

In addition to warnings and disconnection in case of temperature deviations, the devices can also be used as a temperature controller (one-point, two-point or three-point control).

The devices differ from one another in terms of the type and number of connectable temperature sensors.

- **3RS14**: Connection for resistance sensor
- **3RS15**: Connection for thermocouples

<table>
<thead>
<tr>
<th>Function supported</th>
<th>Temperature monitoring relays</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>3RS1440</td>
</tr>
<tr>
<td>Connectable sensor type</td>
<td></td>
</tr>
<tr>
<td>Number of sensors monitored</td>
<td>1</td>
</tr>
<tr>
<td>Resistance sensor</td>
<td>✓</td>
</tr>
<tr>
<td>Thermocouples</td>
<td>--</td>
</tr>
<tr>
<td>Temperature monitoring - overshoot</td>
<td>✓</td>
</tr>
<tr>
<td>Temperature monitoring - undershoot</td>
<td>✓</td>
</tr>
<tr>
<td>Number of adjustable limit values</td>
<td>2</td>
</tr>
</tbody>
</table>

✓ Function supported
-- Function not supported

**Conventional temperature monitoring relays**

Notes:

- Devices required for the communication via IO-Link:
  - Any controller that supports the IO-Link (e.g. ET 200S with CPU or S7-1200), see Catalog ST 70 “Products for Totally Integrated Automation”
  - IO-Link master (e.g. 4SI or 4SI IO-Link electronic module for SIMATIC ET 200S or SM 1278 for S7-1200) see Catalog ST 70 “Products for Totally Integrated Automation”

Each monitoring relay requires an IO-Link channel.

**Temperature monitoring relays for IO-Link**

Notes on safety:

System networking requires suitable protective measures (including network segmentation for IT security) in order to ensure safe plant operation.

More information about the subject of Industrial Security see www.siemens.com/industrialsecurity.
## Overview (continued)

### Connection methods

Selection tables for the 3RS14 and 3RS15 monitoring relays can be found on the following pages.

- Screw terminals
- Spring-type terminals

### More information

#### Characteristic curves

For resistance sensors

The short-circuit and open-circuit detection as well as the measuring range is limited, depending on the sensor type.

- PT100
- PT1000
- KTY83-110
- KTY84
- NTC

#### Measuring ranges for resistance sensors

<table>
<thead>
<tr>
<th>Sensor type</th>
<th>Short circuit</th>
<th>Open circuit</th>
<th>3RS1440, 3RS1441 Measuring range in °C</th>
<th>Measuring range in °F</th>
</tr>
</thead>
<tbody>
<tr>
<td>PT100</td>
<td>✓</td>
<td>✓</td>
<td>-50 ... +750</td>
<td>-58 ... +1 382</td>
</tr>
<tr>
<td>PT1000</td>
<td>✓</td>
<td>✓</td>
<td>-50 ... +500</td>
<td>-58 ... +932</td>
</tr>
<tr>
<td>KTY83-110</td>
<td>✓</td>
<td>✓</td>
<td>-50 ... +175</td>
<td>-58 ... +347</td>
</tr>
<tr>
<td>KTY84</td>
<td>✓</td>
<td>✓</td>
<td>-40 ... +300</td>
<td>-40 ... +572</td>
</tr>
<tr>
<td>NTC1)</td>
<td>✓</td>
<td>–</td>
<td>+80 ... +160</td>
<td>+176 ... +320</td>
</tr>
</tbody>
</table>

- Detection possible
- Detection not possible

1) NTC type: B57227-K333-A1 (100 °C: 1.8 kΩ; 25 °C: 32.762 kΩ).

For thermocouples

- Type “E”
- Type “J”
- Type “K”
- Type “N”
- Type “T”

#### Measuring ranges for thermocouples

<table>
<thead>
<tr>
<th>Sensor type</th>
<th>Short circuit</th>
<th>Open circuit</th>
<th>3RS1540 Measuring range in °C</th>
<th>Measuring range in °F</th>
</tr>
</thead>
<tbody>
<tr>
<td>K</td>
<td>–</td>
<td>✓</td>
<td>-99 ... +1 350</td>
<td>-146.2 ... +2 462</td>
</tr>
<tr>
<td>N</td>
<td>–</td>
<td>✓</td>
<td>-99 ... +1 300</td>
<td>-146.2 ... +2 372</td>
</tr>
<tr>
<td>J</td>
<td>–</td>
<td>✓</td>
<td>-99 ... +1 200</td>
<td>-146.2 ... +2 192</td>
</tr>
<tr>
<td>E</td>
<td>–</td>
<td>✓</td>
<td>-99 ... +999</td>
<td>-146.2 ... +1 830.2</td>
</tr>
<tr>
<td>T</td>
<td>–</td>
<td>✓</td>
<td>-99 ... +400</td>
<td>-146.2 ... +752</td>
</tr>
<tr>
<td>S</td>
<td>–</td>
<td>✓</td>
<td>0 ... 1 750</td>
<td>32 ... 3 182</td>
</tr>
<tr>
<td>R</td>
<td>–</td>
<td>✓</td>
<td>0 ... 1 750</td>
<td>32 ... 3 182</td>
</tr>
<tr>
<td>B</td>
<td>–</td>
<td>✓</td>
<td>400 ... 1 800</td>
<td>752 ... 3 272</td>
</tr>
</tbody>
</table>

- Detection possible
- Detection not possible

#### Note:

SIRIUS 3RS14, 3RS15 temperature monitoring relays for IO-Link

Relays, digitally adjustable for 1 sensor

Overview

The 3RS14 and 3RS15 temperature monitoring relays for IO-Link are used to measure temperatures in solid, liquid and gas media. The temperature is calculated using a sensor in the medium, evaluated by the device and monitored for overshooting or undershooting a working range (window function). The digital temperature monitoring relays have two separately adjustable limit values, are non-volatile and can be operated as desired using the open- or closed-circuit principle.

The devices differ in terms of the number of temperature sensors which can be evaluated. The 3RS1440 and 3RS1540 for IO-Link temperature monitoring relays can be digitally adjusted for one sensor and represent an alternative to temperature controllers in the low-end range (two-point or three-point control).

The devices with two-point control can, for example, be used as a thermostat. The devices with three-point control can, for example, independently switch between heating and cooling.

The 3RS1441 temperature monitoring relays for IO-Link can be digitally adjusted to evaluate up to three resistance sensors at one time. The devices were designed specifically for monitoring motor windings and positions.

The temperature monitoring relays are powered through the control supply voltages IO-Link (L+) and ground (L-) or via an external 24 V DC power supply.

Monitoring

When the temperature has reached the \( \theta_1 \) limit value, the K1 output relay changes its switching state after the configured time \( t \) has expired (output relay K2 reacts accordingly at \( \theta_2 \)). The delay time can be adjusted.

The output relays return immediately to their original state once the temperature reaches the respective hysteresis value.

When the temperature has reached the top \( \theta_1 \) limit value, the K1 output relay changes its switching state after the configured time \( t \) has expired. The output relay returns immediately to its original state once the temperature reaches the respective hysteresis value.

The K2 output relay reacts in the same way at the \( \theta_2 \) lower threshold. Both limit values \( \theta_1 \) and \( \theta_2 \) can be parameterized for overshooting or undershooting the thresholds. This makes it possible to use a limit value for issuing an alarm signal to announce that a limit value is about to be overshot or undershot.

Note:
The "Temperature monitoring mode" parameter can be used to set the desired type of monitoring (monitoring for overshooting or undershooting or range monitoring).

Benefits

- Very simple operation without complicated menu selections
- Two- or three-point control can be parameterized quickly
- All versions with removable terminals
- All versions with screw or spring-type terminals

Application

The temperature monitoring relays can be used in almost any application in which temperature overshoot or undershoot is not permitted, e.g. in the monitoring of set temperature limits and the output of alarm messages for:

- Plant and environment protection
- Temperature limits for process variables e.g. in the packaging industry or electroplating
- Temperature limits for district heating plants
- Exhaust temperature monitoring
- Controlling equipment and machines such as heating, climate and ventilation systems, solar collectors, heat pumps or warm water supplies
- Motor, bearing and gear oil monitoring
- Monitoring of coolants
Selection and ordering data

- To monitor temperatures with a resistance sensor or thermocouple
- Temperature range dependent on sensor type
  - -99 to +1 800 °C or -146.2 to +3 272 °F
- Short-circuit and open-circuit detection in sensor circuit
- Adjustable via IO-Link and locally, with illuminated LCD
- Power supply with 24 V DC via IO-Link or external auxiliary voltage
- Overshoot, undershoot or range monitoring adjustable
- Exact sensor type can be set
- 2 limit values, can be adjusted separately
- Adjustable open/closed-circuit principle
- Can be adjusted by hand or remote RESET (via an external contact)
- Actual value, tripping state for control displayed and conveyed, adjustable in °C or °F
- 1 CO contact per limit value
- 1 CO contact for monitoring sensors and devices

### Sensors

<table>
<thead>
<tr>
<th>Sensory Type</th>
<th>Measuring range (limit of measuring range dependent on sensor)</th>
<th>Hysteresis adjustable for ( I_1 ) and ( I_2 )</th>
<th>Tripping delay time adjustable for ( I_1 ) and ( I_2 ) DELAY</th>
<th>Control supply voltage ( U_s )</th>
<th>Screw terminals</th>
<th>Spring-type terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td>PT100/PT1000, KTY83/KTY84, NTC (resistance sensor)(^1)</td>
<td>-50 ... +750 °C or -58 ... +1 382 °F</td>
<td>0 ... 99</td>
<td>0 ... + 999.9</td>
<td>24</td>
<td>3RS1440-1HB50</td>
<td>3RS1540-1HB80</td>
</tr>
<tr>
<td>( S ), ( S ), ( K ), ( N ), ( R ), ( T ) (thermocouples)</td>
<td>-99 ... + 1 800 °C or -146.2 ... + 3 272 °F</td>
<td>0 ... 99</td>
<td>0 ... + 999.9</td>
<td>24</td>
<td>3RS1540-1HB80</td>
<td>3RS1540-2HB80</td>
</tr>
</tbody>
</table>

\(^1\) NTC type B57227-K333-A1 (100 °C: 1.8 kΩ; 25 °C: 32.762 kΩ).

For accessories see page 5/59.
### Overview

**SIRIUS 3RS14 digital temperature monitoring relay for up to 3 sensors**

The 3RS14 temperature monitoring relays can be used to measure temperatures in solid, liquid and gas media. The temperature is calculated using a sensor in the medium, evaluated by the device and monitored for overshooting or undershooting a working range (window function). The devices can be parameterized to indicate the measured temperature in °C or °F. The 3RS1441 evaluation unit can evaluate up to 3 resistance sensors at the same time.

### Benefits

- Very simple operation without complicated menu selections
- Space-saving with 45 mm width
- Two- or three-point control can be parameterized quickly
- All versions with removable terminals
- All versions with screw or spring-type terminals

### Application

The 3RS1441 temperature monitoring relays can be used almost anywhere where several temperatures must be monitored at one time for overshooting, undershooting or staying within a certain range.

Monitoring of set temperature limits and output of alarm messages for:
- Plant and environment protection
- Temperature limits for process variables e.g. in the packaging industry or electroplating
- Controlling equipment and machines such as heating, climate and ventilation systems, solar collectors, heat pumps or warm water supplies
- Motor, bearing and gear oil monitoring
- Monitoring of coolants

### Selection and ordering data

- For temperature monitoring with up to 3 resistance sensors
- Temperature range dependent on sensor type
  - -50 to +750 °C or -58 to +1382 °F
- Short-circuit and open-circuit detection in sensor circuit
- Adjustable via IO-Link and locally, with illuminated LCD
- Power supply with 24 V DC via IO-Link or external auxiliary voltage
- Overshoot, undershoot or range monitoring adjustable
- Exact sensor type and number of sensors can be set
- 2 limit values, can be adjusted separately
- Adjustable open/closed-circuit principle
- Can be adjusted by hand or remote RESET (via an external contact)
- Actual value, tripping state for control displayed and conveyed, adjustable in °C or °F
- 1 CO contact per limit value
- 1 CO contact for monitoring sensors and devices

### Sensors

<table>
<thead>
<tr>
<th>Sensors</th>
<th>Number of sensors that can be set</th>
<th>Measuring range (limit of measuring range dependent on sensor)</th>
<th>Hysteresis adjustable for ( \alpha_1 ) and ( \alpha_2 )</th>
<th>Tripping delay time adjustable for ( \alpha_1 ) and ( \alpha_2 ) DELAY</th>
<th>Control supply voltage ( U_s )</th>
<th>Screw terminals</th>
<th>Spring-type terminals</th>
</tr>
</thead>
<tbody>
<tr>
<td>PT100/PT1000, KTY83/KTY84, NTC (resistance sensor)</td>
<td>1 ... 3 sensors</td>
<td>-50 ... +750 °C or -58 ... +1382 °F</td>
<td>0 ... 99</td>
<td>0 ... +999.9</td>
<td>24 Ks VDC</td>
<td>3RS1441-1HB50</td>
<td>3RS1441-2HB50</td>
</tr>
</tbody>
</table>

**Temperature monitoring relay, digitally adjustable for up to 3 sensors, non-volatile fault storage can be selected**

1) NTC type: B57227-K333-A1 (100 °C: 1.8 kΩ; 25 °C: 32.762 kΩ).

For accessories see page 5/59.
### Selection and ordering data

<table>
<thead>
<tr>
<th>Use</th>
<th>Version</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Blank labels</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td><img src="image" alt="Blank labels" /> For 3RS14 and 3RS15</td>
<td>Unit labeling plates</td>
<td>3RT2900-1SB20</td>
</tr>
<tr>
<td></td>
<td>For SIRIUS devices</td>
<td></td>
</tr>
<tr>
<td></td>
<td>20 mm x 7 mm, titanium gray¹</td>
<td></td>
</tr>
<tr>
<td><img src="image" alt="Blank labels" /> For 3RS14 and 3RS15</td>
<td>Adhesive labels for SIRIUS devices</td>
<td>3RT1900-1SB60</td>
</tr>
<tr>
<td></td>
<td>19 mm x 6 mm, pastel turquoise</td>
<td></td>
</tr>
<tr>
<td></td>
<td>19 mm x 6 mm, zinc yellow</td>
<td></td>
</tr>
<tr>
<td><img src="image" alt="Blank labels" /> For 3RS14 and 3RS15</td>
<td></td>
<td>3RT1900-1SD60</td>
</tr>
<tr>
<td><strong>Push-in lugs and covers</strong></td>
<td></td>
<td></td>
</tr>
<tr>
<td><img src="image" alt="Push-in lugs" /> For 3RS14 and 3RS15</td>
<td>Push-in lugs</td>
<td>3RP1903</td>
</tr>
<tr>
<td></td>
<td>For screw fixing, 2 units are required for each device</td>
<td></td>
</tr>
<tr>
<td><img src="image" alt="Sealing foil" /> For 3RS14 and 3RS15</td>
<td>Sealing foil</td>
<td>3TK2820-0AA00</td>
</tr>
<tr>
<td></td>
<td>For securing against unauthorized adjustment of setting knobs</td>
<td></td>
</tr>
<tr>
<td><img src="image" alt="Tools for opening spring-type terminals" /> For auxiliary circuit connections</td>
<td>Screwdrivers</td>
<td>3RA2908-1A</td>
</tr>
<tr>
<td></td>
<td>For all SIRIUS devices with spring-type terminals</td>
<td></td>
</tr>
<tr>
<td></td>
<td>3.0 mm x 0.5 mm, length approx. 200 mm, titanium gray/black, partially insulated</td>
<td></td>
</tr>
</tbody>
</table>

¹) PC labeling system for individual inscription of unit labeling plates available from: murrplastik Systemtechnik GmbH
see Catalog IC 10, Chapter 16, "Appendix" ⇒ "External Partners".

Matching sensors see [www.siemens.com/temperature](http://www.siemens.com/temperature).
IO-Link
RFID Systems

Introduction

Overview

The SIMATIC RF200 is the compact RFID system in accordance with ISO 15693 within the SIMATIC RF product family. This system comprises space-saving HF readers (13.45 MHz), which are especially suitable for applications in intralogistics or in small assembly lines.

The readers SIMATIC RF210R, RF220R and RF260R with the interface variant for IO-Link support very simple identification tasks, such as reading an identification number or any user data (“Read Only”). This standardized interface makes it particularly easy and cost-effective to link the data automatically read by the reader into the automation level.

The comprehensive portfolio of extremely rugged, industry-compatible ISO 15693 data carriers from Siemens is available for a wide range of application areas: low-cost Smart Labels for permanent attachment to the product, screw-type transponders for easy mounting (also by robots), or transponders for flush-mounting in metal, for example, on a workpiece carrier.
Overview

SIMATIC RF210R is an M18 reader with integrated antenna. Its extremely compact design makes it ideal for use on small assembly lines.

This reader has either
- an RS-422 interface with transmission procedure 3964R for connection to the RFID communication modules ASM 456, ASM 475, SIMATIC RF160C, RF170C, RF180C and RF182C,
- or a standardized IO-Link interface for connection to IO-Link master modules from Siemens or third parties.

Thanks to its high degree of protection and rugged design, the SIMATIC RF210R reader enables problem-free use even under the toughest industrial conditions. Connection is by means of either an 8-pin M12 plug-in connector (RS422 version) or a 4-pin M12 plug-in connector (IO-Link version).

The reader is operated with ISO 15693-compatible transponders.

Design

Field data

Minimum distance from reader to reader

| SIMATIC RF210R | ≥ 100 mm |

Technical specifications

<table>
<thead>
<tr>
<th>Article No.</th>
<th>6GT2821-1AC32</th>
</tr>
</thead>
<tbody>
<tr>
<td>Product-type designation</td>
<td>RF210R reader IO-Link</td>
</tr>
<tr>
<td>Suitable for installation</td>
<td>ISO 15693 transponder, for connecting to IO-Link master</td>
</tr>
<tr>
<td>Wireless frequencies</td>
<td>Operating frequency rated value</td>
</tr>
<tr>
<td>Electrical data</td>
<td>Range maximum</td>
</tr>
<tr>
<td></td>
<td>Protocol for radio transmission</td>
</tr>
<tr>
<td></td>
<td>Transfer rate with radio transmission maximum</td>
</tr>
<tr>
<td></td>
<td>Product property multilag-capable</td>
</tr>
<tr>
<td></td>
<td>Transmission rate at point-to-point connection serial maximum</td>
</tr>
<tr>
<td></td>
<td>Transmission time for user data</td>
</tr>
<tr>
<td></td>
<td>• for write access per byte typical</td>
</tr>
<tr>
<td></td>
<td>• for read access per byte typical</td>
</tr>
<tr>
<td>Interfaces</td>
<td>Design of the electrical connection</td>
</tr>
<tr>
<td></td>
<td>Standard for interfaces for communication</td>
</tr>
<tr>
<td>Mechanical data</td>
<td>Material</td>
</tr>
<tr>
<td></td>
<td>Color</td>
</tr>
<tr>
<td></td>
<td>Tightening torque of screw for mounting the equipment maximum</td>
</tr>
<tr>
<td></td>
<td>Mounting distance for metal surfaces recommended minimum</td>
</tr>
<tr>
<td>Supply voltage, current consumption, power loss</td>
<td>Supply voltage for DC</td>
</tr>
<tr>
<td></td>
<td>• minimum</td>
</tr>
<tr>
<td></td>
<td>• maximum</td>
</tr>
<tr>
<td></td>
<td>Consumed current at 24 V with DC typical</td>
</tr>
<tr>
<td>Permitted ambient conditions</td>
<td>Ambient temperature</td>
</tr>
<tr>
<td></td>
<td>• during operating</td>
</tr>
<tr>
<td></td>
<td>• during storage</td>
</tr>
<tr>
<td></td>
<td>• during transport</td>
</tr>
<tr>
<td></td>
<td>Protection class IP</td>
</tr>
<tr>
<td></td>
<td>Resistance against shock</td>
</tr>
<tr>
<td></td>
<td>Resistance against shock</td>
</tr>
<tr>
<td></td>
<td>Resistance against vibration</td>
</tr>
</tbody>
</table>
### Technical specifications (continued)

<table>
<thead>
<tr>
<th>Article No.</th>
<th>6GT2821-1AC32</th>
</tr>
</thead>
<tbody>
<tr>
<td>Product-type designation</td>
<td>RF210R reader IO-Link</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Design, dimensions and weight</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Height</td>
<td>83 mm</td>
</tr>
<tr>
<td>Diameter</td>
<td>18 mm</td>
</tr>
<tr>
<td>Net weight</td>
<td>0.065 kg</td>
</tr>
<tr>
<td>Mounting type</td>
<td>2 x M18 nuts (included in scope of supply)</td>
</tr>
<tr>
<td>Cable length for RS 422 interface maximum</td>
<td>-</td>
</tr>
<tr>
<td>Cable length between master and IO-Link device maximum</td>
<td>20 m</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Product properties, functions, components general</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Type of display</td>
<td>3-color LED</td>
</tr>
<tr>
<td>Product feature silicon-free</td>
<td>Yes</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>Standards, specifications, approvals</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Verification of suitability</td>
<td>Wireless according to R&amp;TTE guidelines EN300 330 and EN 301489, FCC, UL/CSA</td>
</tr>
</tbody>
</table>

### Ordering data

<table>
<thead>
<tr>
<th>SIMATIC RF210R reader (IO-Link)</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>6GT2821-1AC32</td>
</tr>
</tbody>
</table>

#### Accessories

**Note:**
All connection options can be found in Chapter 6 "Communication Modules".

<table>
<thead>
<tr>
<th>IO-Link master</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>For SIMATIC ET 200eco PN, for 4 readers.</td>
<td>6ES7148-6JA00-0AB0</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>IO-Link Master 4SI</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>For SIMATIC ET 200S, for 4 readers.</td>
<td>6ES7138-4GA50-0AB0</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>IO-Link connecting cables</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>between IO-Link master and reader, with M12 plug on the IO-Link master, open end, 4-pole, 5 m</td>
<td>6GT2891-4LH50</td>
</tr>
<tr>
<td>between IO-Link master and reader, with M12 plug on the IO-Link master, open end, 4-pole, 10 m</td>
<td>6GT2891-4LN10</td>
</tr>
<tr>
<td>between IO-Link master and reader, with M12 plug at both ends, 4-pole, 5 m</td>
<td>6GT2891-0MH50</td>
</tr>
<tr>
<td>between IO-Link master and reader, with M12 plug at both ends, 4-pole, 10 m</td>
<td>6GT2891-0MN10</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>DVD &quot;RFID Systems Software &amp; Documentation&quot;</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>6GT2080-2AA20</td>
</tr>
</tbody>
</table>

### More information

All current approvals can be found on the Internet at:
http://www.siemens.com/rfid-approvals
Overview

SIMATIC RF220R is an M30 reader with integrated antenna. Its compact design makes it ideal for use in small assembly lines which require a slightly higher range.

This reader has either
- an RS-422 interface with transmission procedure 3964R for connection to the RFID communication modules ASM 456, ASM 475, SIMATIC RF160C, RF170C, RF180C and RF182C,
- or a standardized IO-Link interface for connection to IO-Link master modules from Siemens or third parties.

Thanks to its high degree of protection and rugged design, the SIMATIC RF220R reader enables problem-free use even under the toughest industrial conditions. Connection is by means of either an 8-pin M12 plug-in connector (RS422 version) or a 4-pin M12 plug-in connector (IO-Link version).

The reader is operated with ISO 15693-compatible transponders.

Design

Field data

Minimum distance from reader to reader
SIMATIC RF220R
\[\geq 150 \text{ mm}\]

Technical specifications

<table>
<thead>
<tr>
<th>Article No.</th>
<th>6GT2821-2AC32</th>
</tr>
</thead>
<tbody>
<tr>
<td>Product-type designation</td>
<td>RF220R reader IO-Link</td>
</tr>
</tbody>
</table>

Suitability for installation
ISO 15693 transponder, for connecting to IO-Link master

Wireless frequencies
Operating frequency rated value 13.56 MHz

Electrical data
Range maximum 35 mm
Protocol for radio transmission ISO 15693, ISO 18000-3
Transfer rate with radio transmission maximum 26.5 kbit/s
Product property multitag-capable No
Transmission rate at point-to-point connection serial maximum 38.4 kbit/s
Transmission time for user data
  - for write access per byte typical
  - for read access per byte typical 40 ms

Interfaces
Design of the electrical connection M12, 4-pin
Standard for interfaces for communication IO-Link

Mechanical data
Material Brass, nickel-plated / PBT
Color Silver/pastel turquoise
Tightening torque of screw for mounting the equipment maximum 40 Nm
Mounting distance for metal surfaces recommended minimum 0 mm

Supply voltage, current consumption, power loss
Supply voltage for DC
  - rated value 24 V
  - minimum 20.4 V
  - maximum 28.8 V
Consumed current at 24 V with DC typical 0.05 A

Permitted ambient conditions
Ambient temperature
  - during operating -20 \ldots +70 \, ^\circ\text{C}
  - during storage -25 \ldots +80 \, ^\circ\text{C}
  - during transport -25 \ldots +80 \, ^\circ\text{C}
Protection class IP IP67
Resistance against shock EN 60721-3-7, Class 7 M2
Resistance against shock 500 m/s²
Resistance against vibration 200 m/s²
**IO-Link**  
RFID Systems

**SIMATIC RF220R**

### Technical specifications (continued)

<table>
<thead>
<tr>
<th>Article No.</th>
<th>Product-type designation</th>
<th>Height</th>
<th>Diameter</th>
<th>Net weight</th>
<th>Mounting type</th>
<th>Cable length</th>
<th>Type of display</th>
<th>Product feature silicon-free</th>
<th>Verification of suitability</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td>RF220R reader IO-Link</td>
<td>6GT2821-2AC32</td>
<td>83 mm</td>
<td>30 mm</td>
<td>0.14 kg</td>
<td>2 x M30 nuts (included in scope of supply)</td>
<td>- 20 m</td>
<td>3-color LED</td>
<td>Yes</td>
<td>Wireless according to R&amp;TTE guidelines EN300 330 and EN 301489, FCC, UL/CSA</td>
<td></td>
</tr>
</tbody>
</table>

### Ordering data

<table>
<thead>
<tr>
<th>SIMATIC RF220R reader (IO-Link)</th>
<th>6GT2821-2AC32</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Accessories</strong></td>
<td></td>
</tr>
<tr>
<td>Note: All connection options can be found in Chapter 6 &quot;Communication Modules&quot;.</td>
<td></td>
</tr>
<tr>
<td><strong>IO-Link master</strong></td>
<td>6ES7148-6JA00-0AB0</td>
</tr>
<tr>
<td>For SIMATIC ET 200eco PN, for 4 readers.</td>
<td></td>
</tr>
<tr>
<td><strong>IO-Link Master 4SI</strong></td>
<td>6ES7138-4GA50-0AB0</td>
</tr>
<tr>
<td>For SIMATIC ET 200S, for 4 readers.</td>
<td></td>
</tr>
<tr>
<td><strong>IO-Link connecting cables</strong></td>
<td></td>
</tr>
<tr>
<td>• between IO-Link master and reader, with M12 plug on the IO-Link master, open end, 4-pole, 5 m</td>
<td>6GT2891-4LH50</td>
</tr>
<tr>
<td>• between IO-Link master and reader, with M12 plug on the IO-Link master, open end, 4-pole, 10 m</td>
<td>6GT2891-4LN10</td>
</tr>
<tr>
<td>• between IO-Link master and reader, with M12 plug at both ends, 4-pole, 5 m</td>
<td>6GT2891-0MH50</td>
</tr>
<tr>
<td>• between IO-Link master and reader, with M12 plug at both ends, 4-pole, 10 m</td>
<td>6GT2891-0MN10</td>
</tr>
<tr>
<td><strong>DVD &quot;RFID Systems Software &amp; Documentation&quot;</strong></td>
<td>6GT2080-2AA20</td>
</tr>
</tbody>
</table>

### More information

All current approvals can be found on the Internet at:  
http://www.siemens.com/rfid-approvals
Overview

SIMATIC RF260R is a reader with an integrated antenna. Its compact design makes it ideal for use in assembly lines. This reader has either:

- An RS-422 interface with transmission procedure 3964R for connection to the RFID communication modules ASM 456, ASM 475, SIMATIC RF160C, RF170C, RF180C and RF182C,
- or an RS232 interface with a 3964R transmission procedure or ASCII protocol for connection to S7-1200, PC-based systems or third-party controllers,
- or a standardized IO-Link interface for connection to IO-Link master modules from Siemens or third parties.

Thanks to its high degree of protection and rugged design, the SIMATIC RF260R reader enables problem-free use even under the toughest industrial conditions. Connection is by means of either an 8-pin M12 plug-in connector (RS422/RS232 version) or a 4-pin M12 plug-in connector (IO-Link version).

The reader is operated with ISO 15693-compatible transponders.

Design

Field data

Minimum distance from reader to reader

| SIMATIC RF260R | ≥ 150 mm |

Technical specifications

<table>
<thead>
<tr>
<th>Article No.</th>
<th>6GT2821-6AC32</th>
</tr>
</thead>
<tbody>
<tr>
<td>Product-type designation</td>
<td>RF260R reader IO-Link</td>
</tr>
</tbody>
</table>

Suitability for installation

ISO 15693 transponder, for connecting to IO-Link master

Wireless frequencies

Operating frequency rated value

13.56 MHz

Electrical data

Range maximum

135 mm

Protocol for radio transmission

ISO 15693, ISO 18000-3

Transfer rate with radio transmission maximum

26.5 kbit/s

Product property multitag-capable

No

Transmission rate at point-to-point connection serial maximum

38.4 kbit/s

Transmission time for user data

- for write access per byte typical
- for read access per byte typical

- 40 ms

Interfaces

Design of the electrical connection

M12, 4-pin

Standard for interfaces for communication

IO-Link

Mechanical data

Material

PA6.6

Color

Anthracite

Tightening torque of screw for mounting the equipment maximum

1.5 N·m

Mounting distance for metal surfaces recommended minimum

0 mm

Supply voltage, current consumption, power loss

Supply voltage for DC

- rated value
  24 V
- minimum
  20.4 V
- maximum
  28.8 V

Consumed current at 24 V with DC typical

0.05 A

Permitted ambient conditions

Ambient temperature

- during operating
  -20 ... +70 °C
- during storage
  -25 ... +80 °C
- during transport
  -25 ... +80 °C

Protection class IP

IP67

Resistance against shock

EN 60721-3-7, Class 7 M2

Resistance against shock

500 m/s²

Resistance against vibration

200 m/s²
## IO-Link

**RFID Systems**

### SIMATIC RF260R

<table>
<thead>
<tr>
<th>Technical specifications (continued)</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Article No.</strong></td>
</tr>
<tr>
<td><strong>Product-type designation</strong></td>
</tr>
</tbody>
</table>

- **Design, dimensions and weight**
  - Width: 75 mm
  - Height: 41 mm
  - Depth: 75 mm
  - Diameter: -
  - Net weight: 0.2 kg
  - Mounting type: 2 x M5 screws
  - Cable length: with RS 232 interface maximum
  - for RS 422 interface maximum
  - Cable length between master and IO-Link device maximum: 20 m

- **Product properties, functions, components general**
  - Type of display: 3-color LED
  - Product feature silicon-free: Yes

- **Standards, specifications, approvals**
  - Verification of suitability: Wireless according to R&TTE guidelines EN300 330 and EN 301489, FCC, UL/CSA

### Ordering data

<table>
<thead>
<tr>
<th>SIMATIC RF260R reader (IO-Link)</th>
<th>Article No.</th>
</tr>
</thead>
<tbody>
<tr>
<td></td>
<td>6GT2821-6AC32</td>
</tr>
</tbody>
</table>

**Accessories**

- **RS232 connecting cables**
  - Between reader and PC (RS232), 5 m long, material: PUR, CMG approval.
    - 24 V connection with M12 plug: 6GT2891-4KH50
    - 24 V connection with open ends: 6GT2891-4KH50-0AX0

- **IO-Link master**
  - For SIMATIC ET 200eco PN, for 4 readers: 6ES7138-4GA50-0AB0

- **IO-Link connecting cables**
  - Between IO-Link master and reader, with M12 plug on the IO-Link master, open end, 4-pole, 5 m: 6GT2891-4LH50
  - Between IO-Link master and reader, with M12 plug on the IO-Link master, open end, 4-pole, 10 m: 6GT2891-4LN10
  - Between IO-Link master and reader, with M12 plug at both ends, 4-pole, 5 m: 6GT2891-0MH50
  - Between IO-Link master and reader, with M12 plug at both ends, 4-pole, 10 m: 6GT2891-0MN10

- **DVD “RFID Systems Software & Documentation”**: 6GT2080-2AA20

### More information

All current approvals can be found on the Internet at:

http://www.siemens.com/rfid-approvals